

### M.TECH. IN CAD/CAM COURSE STRUCTURE & SYLLABI

#### SEMESTER – I

	Course	Course Name	Category	Hours per week		Credi	
	codes			L	T	P	ts
1.	21DBS101	Computational Methods	PC	3	0	0	3
2.	21D04101	Advanced Finite Element Methods	PC	3	0	0	3
3.	21D04102a 21D04102b 21D04102c	Program Elective Course - I Computer Integrated Manufacturing Design for Cellular Manufacturing System Design of Hydraulic & Pneumatic System	PE	3	0	0	3
	21D04103a 21D04103b 21D04103c	Program Elective Course – II Advances in Manufacturing Technology Quality Engineering and Manufacturing Computer Aided Process Planning	PE	3	0	0	3
5.	21D04104	Geometric Modeling Laboratory	PC	0	0	4	2
6.	21D04105	Finite Element Analysis Laboratory	PC	0	0	4	2
7.	21DRM101	Research Methodology and IPR	MC	2	0	0	2
8.	21DAC101a 21DAC101b 21DAC101c	Audit Course – I English for Research paper writing Disaster Management Sanskrit for Technical Knowledge	AC	2	0	0	0
		Total					18



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#### SEMESTER – II

S.No.	Course	Course Name	Category	Hours per week		Credit	
	codes			L	T	P	S
1.	21D04201	Advanced Optimization Techniques	PC	3	0	0	3
2.	21D04202	Industrial Robotics and Expert Systems	PC	3	0	0	3
3.	21D04203a 21D04203b 21D04203c	Program Elective Course – III CNC Technology & Programming Computer Graphics Global Integrated Manufacturing	PE	3	0	0	3
4.	21D04204a 21D04204b 21D04204c	Program Elective Course – IV Mechatronics Applications in Manufacturing Rapid Prototyping Artificial Intelligence & Expert Systems	PE	3	0	0	3
5.	21D04205	Process Automation Laboratory	PC	0	0	4	2
6.	21D04206	CAM Laboratory	PC	0	0	4	2
7.	21D04207	Technical seminar	PR	0	0	4	2
8.	21DAC201b	Audit Course – II Pedagogy Studies Stress Management for Yoga Personality Development through Life Enlightenment Skills	AC	2	0	0	0
		Total					18



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#### **SEMSTER - III**

S.No.	Course	Course Name	Category	Hours per week			ategory Hours per w		<b>Credits</b>
	codes			L	T	P			
1.	21D04301a 21D04301b	Program Elective Course – V Advanced Tool Design Design for Manufacturing Computer Aided Tools for Manufacturing	PE	3	0	0	3		
2.	21DOE301c 21DOE301g	Open Elective Business Analytics Internet Of Things Mechatronics	OE	3	0	0	3		
3.	21D04302	Dissertation Phase – I	PR	0	0	20	10		
4.	21D04303	Co-curricular Activities					2		
		Total					18		

#### **SEMESTER - IV**

S.No.	Course	Course Name	Category	Hours per week		<b>Credits</b>	
	codes			L	T	P	
1.	21D04401	Dissertation Phase – II	PR	0	0	32	16
	Total						



### M.TECH. IN CAD/CAM COURSE STRUCTURE & SYLLABI

Course Code	COMPUTATIONAL METHODS	$ \begin{array}{c cccc} DDS & L & T & P \\ \hline 3 & 0 & 0 \end{array} $		P	C				
21DBS101				0	3				
	Semester	I							
Course Objectives: Student will be able to									
Demonstrate a	aptitude in standard numerical techniques for solvingvarious classe	s of	prob	lems.					
• Learn the theo algorithms.	ory underlying the derivation of standard numerical techniques an	d th	e dev	elopi	ment of				
Modeling of e	engineering problems drawn from different disciplines of mechanic	aler	ngine	ering	•				
Course Outcome	s (CO): Student will be able								
	ents to formulate and solve engineering problems that are not a	ımeı	nable	to a	nalytical				
methods. • To demonstrate	the application of numerical methods to data analysis and optimal	desi	gn.						
UNIT – I		Le	cture	Hrs:(	)9				
equations – Matri System of non-line	numerical methods applied to engineering problems: Exartix notation – Determinants and inversion – Iterative methods – ear equations – computer programs  ration: Newton-Cotes integration formulas – Simpson's rules, ion	Rela	axatio	on me	ethods –				
UNIT – II		Le	cture	Hrs:	09				
Optimization: One dimensional unconstrained optimization, multidimensional unconstrained optimization—direct methods and gradient search methods, constrained optimization  Boundary value problems and characteristic value problems: Shooting method—Solution through a set of equations—Derivative boundary conditions—Rayleigh—Ritz method—Characteristic value problems.									
UNIT – III		Le	cture	Hrs:	09				
Numerical solutions of partial differential equations: Laplace's equations – Representations as a difference equation – Iterative methods for Laplace's equations – poisson equation – Examples – Derivative boundary conditions – Irregular and non – rectangular grids – Matrix patterns, sparseness – ADI method – Finite element method.									
UNIT – IV		Le	cture	Hrs:	09				



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**Parabolic partial differential equations:** Explicit method – Crank-Nickelson method – Derivative boundary condition – Stability and convergence criteria – Finite element for heat flow – computer programs.

**Hyperbolic partial differential equations:** Solving wave equation by finite differences- stability of numerical method –method of characteristics-wave equation in two space dimensions-computer programs.

UNIT - V Lecture Hrs: 09

**Curve fitting and approximation of functions:** Least square approximation fitting of non-linear curves by least squares –regression analysis- multiple linear regression, non linear regression - computer programs.

#### **Textbooks:**

- 1. "Numerical Methods for Engineers", Steven C.Chapra, Raymond P.Canale Tata Mc-Graw hill
- 2. "Applied numerical analysis", Curtis F.Gerald, partick.O. Wheatly Addison-wesley, 1989
- 3. "Numerical methods", Douglas J..Faires, Riched Burden Brooks/cole publishing company, 1998. Second edition.

#### **Reference Books:**

- 1. "Numerical mathematics and computing", Ward cheney & David Kincaid Brooks/Cole publishing company 1999, fourth edition.
- 2. "Mathematical methods for physics and engineering" Riley K.F.M.P.Hobson. & Bence
- S.J.Cambridge university press,1999.



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	COURSE STRUCTURE & STEELABI				
Course Code	ADVANCED FINITE ELEMENT METHODS	L	T	P	C
21D04101		3	0	0	3
	Semester	I			
Course Objective	0.00				
Course Objective	55.				
You learn mo	dern analysis techniques used widely in engineering practice and	the	scien	ces, a	and you
use these tech	niques in a general finite element program.				
	w to establish computational models of problems of solids and f	luid	s, sol	ve th	em on
* * *	nd assess the accuracy of the results.				
_	e on your knowledge of mechanics, reinforce your knowledge, an		_		
_	ackled numerically on the computer. Great knowledge in your to	ol b	OX W	hatev	er you
goals.					
Course Outcome	s (CO): Student will be able to				
- C4d4	learn the moth anotical farmulation of the finite alament mothed a	1 1	l-		.1 :4
	learn the mathematical formulation of the finite element method a	ına ı	now t	o app	ory it
	r) ordinary and partial differential equations.				
_	roblems. & 2- D Structural & Heat Transfer Problems using FEA				
	& Beams Problems using FEA				
	solve structural & dynamics problems	T		T T	00
UNIT - I		Le	cture	Hrs:	09
Formulation Tec	hniques: Methodology, Engineering problems and governing diff	fere	ntial	equat	ions,
finite elements., V	Variational methods-potential energy method, Raleigh Ritz method	d, st	rong	and v	weak
forms, Galerkin a	nd weighted residual methods, calculus of variations, Essential an	d na	ıtural	boun	dary
conditions.					
		T		T T	00
UNIT - II		Le	cture	Hrs:	09
One-dimensional	finite element methods: Bar elements, temperature effects.	Ele	ment	matr	rices,
assembling of glo	obal stiffness matrix, Application of boundary conditions, Elimin	natio	on an	d pe	nalty
approaches, solut	ion for displacements, reaction, stresses, temperature effects, (	<b>Q</b> uac	lratic	Elen	nent,
Heat transfer pro	blems: One-dimensional, conduction and convection problems.	. Ex	ampl	es: -	one
dimensional fin,					
UNIT - III		Le	cture	Hrs:	09
	matrices, assembling of global stiffness matrix, solution for displa	acen	nents,	reac	tion,
stresses, temperat	uic chous.				

Beams and Frames: Element matrices, assembling of global stiffness matrix, solution for

displacements, reaction, stresses.



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UNIT - IV		Lecture Hrs: 09							
<b>Two dimensional problems:</b> CST, LST, four noded and eight nodded rectangular elements, Lagrange basis for triangles and rectangles, serendipity interpolation functions. Axisymmetric Problems: Axisymmetric formulations, Element matrices, boundary conditions. Heat Transfer problems: Conduction and convection, examples: - two-dimensional fin.									
Isoparametric for integration.	rmulation: Concepts, sub parametric, super parametric ele								
UNIT - V		Lecture Hrs: 09							
solution methods,	in Structural Dynamics: Dynamic equations, eigen value pr simple problems. equirements for convergence, h-refinement and p-refinement								
	plation functions, pascal's triangle.	it, complete and							
Textbooks:									
2012A 2. Concepts an	to Finite element methods by Chandraputla & Ashok D.Belaga d Applications of Finite Element Analysis By Robert D. Cook, I Plesha, Robert J. Witt	·							
Reference Books									
<ul><li>2. Finite Elemen</li><li>3. Finite Elemen</li></ul>	t method in Heat transfer and fluid dynamics, J.N.Reddy, CRC pret Method, Zienckiwicz O.C. & R. L. Taylor, McGraw-Hill, 1983. t of Nonlinear continua, . J. N. Oden, McGraw-Hill, New York, 19t procedures, K. J. Bathe, Prentice-Hall, 1996.								
Online Learning	Resources:								
<ul><li>ht</li><li>ht</li><li>ht</li></ul>	https://nptel.ac.in/courses/112/104/112104193/ https://nptel.ac.in/courses/112/104/112104205/ https://nptel.ac.in/courses/105/105/105105041/ https://nptel.ac.in/courses/112/106/112106130/ https://nptel.ac.in/courses/112/103/112103295/								

Course Code	COMPUTER INTEGRATED MANUFACTURING	L	T	P	C
21D04102a	Program Elective Course - I	3	0	0	3



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	Semester I						
Course Objectives: Student will be able							
<ul> <li>To gain knowledge about the basic fundamental of CAD.</li> <li>To gain knowledge on how computers are integrated at various levels of planning and manufacturing understand computer aided planning and control and computer monitoring.</li> </ul>							
	s (CO): Student will be able to						
control, Com	ne importance of product development through CIM. Get know puter Integrated Manufacturing and Automation.						
	riate material handling and storage in an automated manufacturing methods of utilization of appropriate features in CAD appropriate.						
UNIT - I	Unit – I Introduction:	Lecture Hrs:09					
Fundamental concepts in Manufacturing and Automation, Automation Strategies, Economic analysis in production, fundamentals of CAD / CAM, product cycle and CAD/CAM, Automation and CAD/CAM, Scope of CIM, Automated flow lines, Transfer mechanisms, methods of Line balancing.  Numerical control machines: Introduction- basic components of an NC system-the NC procedure- NC coordinate system, NC motion control system- application of numerical control- Economics of Numerical control.							
UNIT - II	Unit – II NC part programming:	Lecture Hrs: 09					
Introduction - The with manual data	e Bunch tape in NC - Tape code format - manual part programmin input.	g. NC programming					
UNIT - III	Unit – III Computer controls in NC:	Lecture Hrs: 09					
Group Technolog	chnology - Computer Numerical Control (CNC), Direct Numerica gy: Part families, parts classification and coding, production flow hine cell design, benefits of GT						
UNIT - IV	Unit – IV Flexible Manufacturing Systems	Lecture Hrs: 09					
Components of FMS, FMS Work stations, Material Handling Systems, and Computer Control system, FMS layout configurations and benefits of FMS.  Computer aided planning systems: Approaches to Computer aided Process Planning (CAPP) - Generative and Retrieval CAPP systems, benefits of CAPP, Material Requirement Planning (MRP), mechanism of MRP, benefits, and Capacity Planning.							
UNIT - V	Computer integrated manufacturing	Lecture Hrs: 09					
system, application	machining systems. adaptive control optimization system, adaptions to machining processes, computer process monitoring, hierafacturing, and computer process control.						



#### M.TECH. IN CAD/CAM COURSE STRUCTURE & SYLLABI

#### **Textbooks:**

1. Automation, Production systems and Computer Integrated Manufacturing Systems – Mikel P.Groover, PHI Publishers

#### **Reference Books:**

- 1. CAD/CAM Mikell P.Groover, and Emory W. Zimmers.Jr. PHI Publishers
- 2. Computer Aided Design and Manufacturing, K.Lalit Narayan, K.Mallikarjuna Rao, MMM Sarcar, PHI Publishers
- 3. CAD/CAM/CIM, Radhakrishnan and Subramanian, New Age Publishers

- 1.https://en.wikipedia.org/wiki/Computer-integrated manufacturing
- 2. https://www.techopedia.com/definition/30965/computer-integrated-manufacturing-cim
- 3. https://www.youtube.com/watch?v=\_OaBMsUgqgQ
- 4. https://www.youtube.com/watch?v=edplvB\_Xvso
- 5. https://nptel.ac.in/courses/112/104/112104289/
- 6. https://www.youtube.com/watch?v=9fqygvj-O2s.

Course Code	DESIGN FOR CELLULAR MANUFACTURING	L	T	P	C
21D04102b	SYSTEM (PE-I)	3	0	0	3
Semester					



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Course Objectives: Student will be able to

• To impart knowledge on group technology, optimization algorithms, implementation of GT/CMS, Performance measurements and economical aspects of CMS.

#### **Course Outcomes (CO):**

At the end of this course the student should be able to understand

- Concepts and applications of Cellular manufacturing systems
- Traditional and non-traditional approaches of Problem solving
- Performance measurement

<ul> <li>Performance</li> </ul>	e measurement								
Human and	economical aspects of CMS.								
UNIT - I	- I INTRODUCTION Lecture Hrs:09								
Introduction to	Group Technology, Limitations of traditional manufacturing system	ns, characteristics and							
design of groups	s, benefits of GT and issues in GT.								
UNIT - II	CMS PLANNING AND DESIGN	Lecture Hrs:09							
D 11 1 G									
	/CMS - Design of CMS - Models, traditional approaches and non-tr	raditional approaches -							
Genetic Algorith	nms, Simulated Annealing, Neural networks								
UNIT - III	IMPLEMENTATION OF GT/CMS	Lecture Hrs:09							
Inter and Inter	cell largest and non-cost based models, establishing a team	annuach Managarial							
	cell layout, cost and non-cost based models, establishing a team	approach, Manageriai							
structure and gro	oups, batch sequencing and sizing, life cycle issues in GT/CMS								
UNIT - IV	PERFORMANCE MEASUREMENT AND CONTROL	Lecture Hrs:09							
UNII - IV	PERFORMANCE MEASUREMENT AND CONTROL	Lecture firs.09							
Measuring CMS	performance - Parametric analysis - PBC in GT/CMS, cell loading,	GT and							
MRP - framewo		OT and							
UNIT - V	ECONOMICS OF GT/CMS	Lecture Hrs:09							
CIVII	Decivorines of Giverns	Lecture This.09							
Conventional Vs group use of computer modelss in GT/CMS, Human aspects of GT/CMS - cases.									
	C 1 Part Land Land Land Land Land Land Land Land								
Text Books:									

- 1. Askin, R.G. and Vakharia, A.J., G.T "Planning and Operation, in The automated factory-Hand Book: Technology and Management ", Cleland.D.I. and Bidananda, B (Eds), TAB Books, NY, 1991.
- 2. Kamrani, A.K, Parsaei, H.R and Liles, D.H. (Eds), "Planning, design and analysis of cellular manufacturing systems", Elsevier, 1995.

#### **Reference Books:**



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1. Burbidge, J.L. Group "Technology in Engineering Industry ", Mechanical Engineering pub.London, 1979. 2. Irani, S.A. "Cellular Manufacturing Systems ", Hand Book.

#### **Online Learning Resources:**

- https://nptel.ac.in/courses/110/106/110106044/
- https://www.youtube.com/watch?v=toTYb7Sirm0
- https://www.youtube.com/watch?v=Ynhp8Wi2qwM
- https://nptel.ac.in/courses/112/104/112104188/
- https://nptel.ac.in/courses/110/107/110107141/
- https://www.youtube.com/watch?v=voN\_297SXD8

<b>Course Code</b>	DESIGN OF HYDRAULIC AND PNEUMATIC	L	T	P	C
21D04102c	SYSTEMS (PE-I)	3	0	0	3
	Semester				
Course Objecti	ves:				

• Power in Industry. Also to impart knowledge on the methodology of basic and advanced design of pneumatics and hydraulics systems.



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• It helps students to get knowledge on the n	eed, use and appl	ication of fluid power.
Course Outcomes (CO): Student will be able	to	
Familiar to industrial design that lead to au	tomation.	
• To impartstudents on the science, use and	application of hyd	raulics and pneumatics as fluid.
UNIT – I		Lecture Hrs:09
OIL HYDRAULIC SYSTEMS AND HYDR	AULIC ACTUA	TORS
Hydraulic Power Generators - Selection and	specification of p	numps, pump characteristics. Linear
and Rotary Actuators – selection, specification	and characteristic	es.
UNIT – II		Lecture Hrs: 09
CONTROL AND REGULATION ELEMENT	NTS	
Pressure - direction and flow control valves -	relief valves, non	-return and safety valves - actuation
systems.		
UNIT – III		Lecture Hrs: 09
HYDRAULIC CIRCUITS  Reciprocation, quick return, sequencing, syncircuits - press circuits - hydraulic milling mover circuits - design and selection of components	nachine - grindin	g, planning, copying, - forklift, earth
UNIT – IV		Lecture Hrs: 09
PNEUMATIC SYSTEMS AND CIRCUITS Pneumatic fundamentals - control elements, pocircuits - fringe conditions modules and these mapping methods - step counter method - com	osition and pressu e integration - sec	quential circuits - cascade methods -
UNIT – V		Lecture Hrs: 09
INSTALLATION, MAINTENANCE AND a Pneumatic equipments- selection of componer hydro pneumatic circuits - use of microproce Robotic circuits.  Textbooks:	nts - design calcu	lations – application -fault finding -
1. Andrew Parr, "Hydraulic and Pneumatics" 2. Bolton. W., "Pneumatic and Hydraulic Sy		



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#### Reference Books:

- 1. Antony Espossito, "Fluid Power with Applications", Prentice Hall, 1980.
- 2. Dudleyt, A. Pease and John J. Pippenger, "Basic fluid power", Prentice Hall, 1987.
- 3. K.Shanmuga Sundaram, "Hydraulic and Pneumatic Controls: Understanding made Easy" S.Chand & Co Book publishers, New Delhi, 2006 (Reprint 2009).

#### **Online Learning Resources:**

- https://nptel.ac.in/courses/112/103/112103249/
- https://nptel.ac.in/courses/112/106/112106175/
- https://nptel.ac.in/content/storage2/courses/112106175/Module%201/Lecture%201.pdf
- https://www.vidyarthiplus.com/vp/attachment.php?aid=18972
- https://snscourseware.org/snscenew/notes.php?cw=CW\_5e27ec3b0457a

Course Code	ADVANCES IN MANUFACTURING TECHNOLOGY	L	T	P	C
21D04103a	Program Elective Course - II	3	0	0	3
	Semester	I			

#### Course Objectives: Students able to

- Understand the "Technology Generation and Practical Deployment for enabling industries to face global competition" as opposed to "Technology Acquisition and Adoption".
- Provide an integrated, effective and practical platform for
- Create facilities for teaching, training and research & development work for post-graduate studies in various fields of manufacturing technology
- Link up with national and international colleges/ universities of excellence to impart the education,



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maintain quality & content of curriculum and award degree certificates in post-Graduation / Doctorates

• Provide facilities for international and national subject experts to stay, teach and conduct research projects / programmes on mutual exchange and recognition basis

#### Course Outcomes (CO): Students able to

- Analyze technical problems, propose solutions and document with written and oral reports.
- Employ technology for communications, data collection, analysis, simulation and control.
- Use Basic Project management skills, project team work and ethical behavior.
- Machine variety materials using a conversational and CNC lathe, milling machine and grinder.
- Use the basic manufacturing methods, measurements, automation and quality control.
- Code PLCs and micro controllers for networking and system control applications.
- Apply engineering design and project management principles.
- Use CAD/CAM and apply it to engineering graphics and mechanical design.
- Apply the basics of engineering materials, structures and to mechanical design.
- Read blueprints, perform component measurements and utilize the Machinery's Handbook.

UNIT - I	<b>Surface Processing Operations</b>	Lecture Hrs: 09
		i

Plating and Related Processes, Conversion Coatings, Physical Vapor Deposition, Chemical Vapor Deposition, Organic Coatings, Porcelain Enameling and other Ceramic coatings, Thermal and Mechanical Coating Processes.

### UNIT - II Un-conventional Machining Methods Lecture Hrs: 09

Abrasive jet machining - Elements of the process, mechanics of metal removal process parameters, economic considerations, applications and limitations, recent developments. Ultrasonic machining: Elements of the process, machining parameters, effect of parameters on surface finish and metal removal rate, mechanics of metal removal process parameters, economic considerations, applications and limitations.

UNIT - III Electro-Chemical Processes Lecture Hrs: 09

**Electro-Chemical Processes**: Fundamentals of electro chemical machining, metal removal rate in ECM, Tool design, Surface finish and accuracy economics aspects of ECM.

Wire EDM Process: General Principle and applications of Wire EDM, Mechanics of metal removal, Process parameters, selection of tool electrode and dielectric fluids, methods surface finish and machining accuracy.

UNIT - IV Electron Beam Machining Lecture Hrs: 09

Generation and control of electron beam for machining, theory of electron beam machining, principle, advantages, limitations, comparison of thermal and non-thermal processes.

Plasma Arc Machining: Principle, machining parameters, effect of machining parameters on surface finish and metal removal rate, applications, limitations

UNIT - V	Laser Beam Machining	Lecture Hrs: 09



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Principle, effect of machining parameters on surface finish, applications, and limitations.

**Rapid Prototyping:** Working principle, methods-Steriolithography, Laser sintering, Fused deposition method, applications and limitations.

#### **Text Books:**

- 1. Manufacturing Technology P. N. Rao, TMH Publishers
- 2. Fundamentals of Modern Manufacturing, Mikell P. Groover, John Wiley & Sons Publishers

#### **Reference Books:**

- 1.Production Technology HMT
- 2. Manufacturing Science Cambel
- 3. Welding Technology R.S, Parmar,
- 4. Introduction to Nanotechnology Poole and Owens, Wiley (2003). Outcomes

- https://nptel.ac.in/courses/112/107/112107078/
- https://youtu.be/t3y\_Ys3LgGM
- https://www.youtube.com/watch?v=E4VZ\_rFqpG4&t=1s
- https://youtu.be/-tcaR7oSx\_w
- https://youtu.be/Uybg6VDLoRQ
- https://youtu.be/Uybg6VDLoRO
- https://youtu.be/aWQsEX1TrSI

Course Code	QUALITY ENGINEERING AND MANUFACTURING	L	T	P	C	
21D04103b	Program Elective Course - II	3	0	0	3	
	Semester	I				
Course Objective	Course Objectives: Student will be able to					
• To impart through knowledge in various latest measurement systems such as laser metrology, coordinate measuring machines and electro-optical devices. To train them in the area of precision and quality manufacturing						
Course Outcome	s (CO): Student will be able to					
• Know the importance of the quality in their life and can make it as their habbit in all their activities.					ities.	
UNIT - I	Quality value and Engineering	Lec	cture	Hrs:	)9	



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An overall quality system, quality engineering in production design, quality engineering in design production processes

UNIT - II Loss function and quality level Lecture Hrs: 09

Derivation and use of quadratile loss function, economic consequences of tightening tolerances as a means to improve quality, evaluations and types tolerances (N-type-, S-type and L-type)

**UNIT - III** Tolerance Design and Tolerancing

Lecture Hrs: 09

Functional limits, tolerance design for N-type, L-type and S-type characteristics, tolerance allocation for multiple components.

**Parameter and tolerance design:** Introduction to parameter design, signal to noise ratios, parameter design strategy, Introduction to tolerance design, tolerance design using the loss function, identification of tolerance design factors.

UNIT - IV Design of Experiments

Lecture Hrs: 09

Introduction, Task aids and Responsibilities for DOE process steps, DOE process steps description.

**Analysis of variance (ANOVA):** no-WAY ANOVA, One-way ANOVA, two-way ANOVA, Critique of F-test, ANOVA for four level factors, multiple level factors.

UNIT - V Orthogonal Arrays

Lecture Hrs: 09

Typical test strategies, better test strategies, efficient test strategies, conducting and analyzing an experiment.

**Interpolation of experimental results:** Interpretation methods, percent contribution, estimating the mean

**ISO-9000** Quality system, BDRE, 6-sigma, bench marking, quality circles-brain storming-fishbone diagram-problem analysis.

#### **Text Books:**

1. Taguchi techniques for quality engineering/Philip J.Ross / McGraw Hill Intl. 2nd Edition, 1995.

#### **Reference Books:**

- 1. Quality Engineering in Production systems/G.Taguchi, A.Elasayed et al/Mc.Graw Hill Intl. Edition, 1989.
- 2. Taguchi methods explained: Practical steps to Robust Design/Papan P.Bagchi/Prentice Hall Ind. Pvt. Ltd. New Delhi.

- https://quality-one.com/quality-engineering/
- https://en.wikipedia.org/wiki/Ouality\_engineering
- https://youtu.be/5 hng9rgVHE
- https://www.youtube.com/watch?v=oIG NDb2g3U



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- https://nptel.ac.in/courses/110/104/110104080/
- https://nptel.ac.in/courses/110/105/110105088/

<b>Course Code</b>	COMPUTER AIDED PROCESS PLANNING	L	T	P	C
21D04103c	Program Elective Course - II	3	0	0	3
	Semester	I			

#### Course Objectives: Student will be able

- To know the various steps involved in CAPP
- To classify the various methods of CAPP
- To understand the feature recognition in CAP
- Notable requirements for process planning systems are consistency, accuracy, and ease of application and completeness.

#### **Course Outcomes (CO):**

- Generate the structure of automated process planning system and uses the principle of generative and retrieval CAPP systems for automation
- Select the manufacturing sequence and explains the reduction of total set up cost for a particular sequence
- Predict the effect of machining parameters on production rate, cost and surface quality and determines



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the manufacturing tolerances

- Explain the generation of tool path and solve optimization models of machining processes
- Create awareness about the implementation techniques for CAPP

#### UNIT - I Introduction to CAPP

Lecture Hrs: 09

Information requirement for process planning system, Role of process planning, advantages of conventional process planning over CAPP, Structure of Automated process planning system, feature recognition, methods.

**Generative CAPP system:** Importance, principle of Generative CAPP system, automation of logical decisions, Knowledge based systems, Inference Engine, implementation, benefits.

#### UNIT - II Retrieval CAPP system

Lecture Hrs: 09

Significance, group technology, structure, relative advantages, implementation, and applications **Selection of manufacturing sequence:** Significance, alternative manufacturing processes, reduction of total set-up cost for a particular sequence, quantitative methods for optimal selection, examples.

#### **UNIT - III Determination of machining parameters**

Lecture Hrs: 09

Reasons for optimal selection of machining parameters, effect of parameters on production rate, cost and surface quality, different approaches, advantages of mathematical approach over conventional approach, solving optimization models of machining processes.

**Determination of manufacturing tolerances:** design tolerances, manufacturing tolerances, methods of tolerance allocation, sequential approach, integration of design and manufacturing tolerances, advantages of integrated approach over sequential approach

#### UNIT - IV Generation of tool path

Lecture Hrs: 09

Simulation of machining processes, NC tool path generation, graphical implementation, determination of optimal index positions for executing fixed sequence, quantitative methods.

#### UNIT - V Implementation techniques for CAPP

Lecture Hrs: 09

MIPLAN system, Computer programming languages for CAPP, criteria for selecting a CAPP system and benefits of CAPP. Computer integrated planning systems, and Capacity planning system.

#### **Text Books:**

 $1 Automation \ , \ Production \ systems \ and \ Computer \ Integrated \ Manufacturing \ System \ -Mikell \ P. Groover$ 

2.. Computer Aided Design and Manufacturing – Dr. Sadhu Singh.

#### Reference Books:

1. Computer Aided Engineering – David Bedworth

#### **Online Learning Resources:**

https://nptel.ac.in/courses/112/104/112104188/



#### M.TECH. IN CAD/CAM COURSE STRUCTURE & SYLLABI

- https://www.youtube.com/watch?v=20\_K7c65Swg
- https://www.youtube.com/watch?v=y24meNZbUoU
- https://youtu.be/PRjExZxWsNc
- https://nptel.ac.in/courses/103/103/103103164/

Course Cod	GEOMETRIC MODELLING LABORATORY	L	T	P	C
21D04104		0	0	4	2
	Semester	I			
Course Obj	ectives: Student will be able				
To train	he students with CAD packages				
	t the 2D and 3D modeling skills to the students.				
• To impo	t and export different IGES files from one software to another				
Course Out	comes (CO):				
• Students	will be able to design different parts of mechanical equipments				
• Students	will be able to apply their skills in various designing and Manufacturi	ng Ir	dustr	ies.	
List of Exp	riments:				



#### M.TECH. IN CAD/CAM COURSE STRUCTURE & SYLLABI

#### A - MODELLING

- 1.Generation of the following curves using "C" language
- i. Bezier curves
- ii. Splines
- iii. B-Splines
- 2.Generation of the following surfaces using "C" language
- i. Bezier surfaces
- ii. B-Splines surfaces
- 3. Generation of solids using "C"
- i. Constructive solid geometry
- ii. Boundary representation
- 4. Typical tasks of Modeling using PRO/E,IDEAS, CATIA solid modeling packages

Surface modeling Solid Modeling Drafting and Assembly Module

Course Code	FINITE ELEMENT ANALYSIS LABORATORY	L	T	P	C
21D04105		0	0	4	2
	Semester	Ι			

#### **Course Objectives:**

• Students should use the commercial software or programmes form the text-books or self-developed programs, to verify the results obtained by manual calculations. The input data and output results of the problem solved using the computer programs should be included in the Journal.

#### Course Outcomes (CO): Student will be able to

- Select appropriate element for given problem
- Select suitable meshing and perform convergence test
- Select appropriate solver for given problem
- Interpret the result
- Apply basic aspects of FEA to solve engineering problems



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Validate FEA solution

#### **List of Experiments:**

Finite Element Analysis using ANSYS 14.5 Package for different structures the discretization can be done with 1-D, 2-D & 3-D elements to perform the following analysis:

- 1. Static Analysis
  - a. Stress analysis of 2D truss.
  - b. Stress analysis of a plate with a circular hole and L-Bracket 2D and 3D
  - c. Stress analysis of beams (cantilever, simply supported & fixed ends)
  - d. Stress analysis of an axi-symmetric component
- 2. Thermal and Fluid flow Analysis
  - a. Conductive heat transfer analysis of a 2D and 3D components
  - b. Convective heat transfer analysis of a 2D component
  - c. Coupled field analysis of a component
  - d. Determination of velocity of a fluid and volumetric flow rates for 1-D Fluid flow
  - e. Determination of velocity of a fluid and volumetric flow rates for 2-D Fluid flow
- 3. Modal Analysis
  - a. mode frequency analysis of a 2D component
  - b. mode frequency analysis of beams (cantilever, simply supported, fixed ends)
- 4. Transient analysis
  - a. Transient analysis of a cantilever beam
- 5. FEM through MAT LAB
- a. Introduction to MAT LAB
- b. Analysis of 1-dimesional & 2D dimensional truss.
- c. Analysis of 1-dimesional & 2D dimensional beam. d. Analysis of 1-dimesional & 2D dimensional heat conduction.



#### M.TECH. IN CAD/CAM COURSE STRUCTURE & SYLLABI

Lab Manual		



engineering students"

## JAWAHARLAL NEHRU TECHNOLOGICAL UNIVERSITY ANANTAPUR (Established by Govt. of A.P., ACT No.30 of 2008) ANANTHAPURAMU – 515 002 (A.P) INDIA

### M.TECH. IN CAD/CAM COURSE STRUCTURE & SYLLABI

Course Code	RESEARCH METHODOLOG	Y AND IPR	L	T	P	C
21DRM101			2	0	0	2
		Semester			I	
Course Objective	es:					
<ul> <li>Identify a</li> </ul>	n appropriate research problem in their interes	ing domain.				
<ul> <li>Understar</li> </ul>	nd ethical issues understand the Preparation of	a research project the	esis rej	ort.		
<ul> <li>Understar</li> </ul>	nd the Preparation of a research project thesis r	eport				
<ul> <li>Understar</li> </ul>	nd the law of patent and copyrights.					
<ul> <li>Understar</li> </ul>	nd the Adequate knowledge on IPR					
	s (CO): Student will be able to					
	research related information					
· ·	search ethics					
<ul> <li>Understar</li> </ul>	nd that today's world is controlled by Compu	iter, Information Te	chnolo	gv. bu	t tom	orrow
	l be ruled by ideas, concept, and creativity.	,		<i>63</i>		
	nding that when IPR would take such importar	t place in growth of	indivi	duals &	z natio	n. it is
	to emphasis the need of information about Inte					
	n general & engineering in particular.	1	0	•		,
	nd that IPR protection provides an incentive	e to inventors for f	urther	resear	ch wor	k and
	nt in R & D, which leads to creation of new					
	growth and social benefits.	•				
UNIT - I		Lecture Hrs:				
Meaning of rese	arch problem, Sources of research problem,	Criteria Character	istics	of a g	ood re	search
problem, Errors i	n selecting a research problem, scope, and ol	jectives of research	probl	em. A	pproac	hes of
-	solutions for research problem, data co	llection, analysis,	interp	retatior	n, Nec	essary
instrumentations						
UNIT - II		Lecture Hrs:				
	e studies approaches, analysis Plagiarism, Re					-
_	Paper Developing a Research Proposal, For	mat of research pro	posal,	a pres	sentatio	n and
assessment by a re	eview committee.					
UNIT - III		Lecture Hrs:				
	tual Property: Patents, Designs, Trade and Cop					
	earch, innovation, patenting, development. In		Interi	nationa	l coope	ration
	operty. Procedure for grants of patents, Patentin					
UNIT - IV		Lecture Hrs:				
	ope of Patent Rights. Licensing and transfer of	technology. Patent	inform	ation a	nd data	ıbases
Geographical Indi	cations.					
UNIT - V						
_	nts in IPR: Administration of Patent System.	_		i; IPR	of Biol	ogica
	er Software etc. Traditional knowledge Case S	tudies, IPR and IITs.				
Textbooks:						

1. Stuart Melville and Wayne Goddard, "Research methodology: an introduction for science &



#### M.TECH. IN CAD/CAM COURSE STRUCTURE & SYLLABI

2. Wayne Goddard and Stuart Melville, "Research Methodology: An Introduction"

#### **Reference Books:**

- 1. Ranjit Kumar, 2nd Edition, "Research Methodology: A Step by Step Guide for beginners"
- 2. Halbert, "Resisting Intellectual Property", Taylor & Earn; Francis Ltd ,2007.
- 3. Mayall, "Industrial Design", McGraw Hill, 1992.
- 4. Niebel, "Product Design", McGraw Hill, 1974.
- 5. Asimov, "Introduction to Design", Prentice Hall, 1962.
- 6. Robert P. Merges, Peter S. Menell, Mark A. Lemley, "Intellectual Property in New Technological Age", 2016.



### M.TECH. IN CAD/CAM COURSE STRUCTURE & SYLLABI

<b>Course Code</b>	rse Code ADVANCED OPTIMIZATION TECHNIQUES		T	P	С					
21D04201	01		0	0	3					
	Semester II									
Course Objectives: Student will be able to										
• To understand the theory of optimization methods and algorithms developed for solving various types										
•	of optimization problems  To develop and promote research interest in applying optimization techniques in problems of									
	To develop and promote research interest in applying optimization techniques in problems of Engineering and Technology									
	mathematical results and numerical techniques of optimization	on fl	heory	to	concrete					
engineering pr		)II (I	ileor y		concrete					
	s (CO): Student will be able to									
	nportance of optimization of industrial process management									
* * *	oncepts of mathematics to formulate an optimization problem									
Analyse and a	appreciate variety of performance measures for various optimization	n pr	oblen	ns						
UNIT - I	INTRODUCTION AND ROBOT KINEMATICS	Lec	cture	Hrs:(	)9					
Linear programn	ning: Two-phase simplex method, Big-M method, duality, interpr	etati	on, a	pplica	ations.					
	olem: Hungarian's algorithm, Degeneracy, applications, unbalanc									
salesman problem		•								
UNIT - II	ROBOT DRIVES AND CONTROL	Lec	cture	Hrs:	09					
Classical antimiz	ration techniques: Single variable optimization with and withou	ut co	netre	inte	multi _					
	<b>Classical optimization techniques:</b> Single variable optimization with and without constraints, multi – variable optimization without constraints, multi – variable optimization with constraints – method of									
Lagrange multipliers, Kuhn-Tucker conditions.										
UNIT - III	ROBOT SENSORS	Leo	cture	Hrs:	09					
	ods for optimization: Nelder Mead's Simplex search method, C				unction,					
	nethod, Newton's method, types of penalty methods for handling									
UNIT - IV	ROBOT CELL DESIGN AND APPLICATION	Leo	cture	Hrs:	09					
Genetic algorith	mm (GA): Differences and similarities between convention	nal	and	evol	utionary					
	king principle, reproduction, crossover, mutation, termination			ia,	different					
	crossover operators, GA for constrained optimization, draw backs									
	mming (GP): Principles of genetic programming, terminal									
differences between	en GA & GP, random population generation, solving differential e	quat	ions i	ısıng	GP.					
UNIT - V	ROBOT PROGRAMMING, ARTIFICIAL	Lec	cture	Hrs:	09					
	INTELLIGENCE AND EXPERT SYSTEMS									
Dominated sorted	GA, convergence criterion, applications of multi-objective proble	ms .								



#### M.TECH. IN CAD/CAM COURSE STRUCTURE & SYLLABI

**Applications of Optimization in Design and Manufacturing systems:** Some typical applications like optimization of path synthesis of a four-bar mechanism, minimization of weight of a cantilever beam, optimization of springs and gears, general optimization model of a machining process, optimization of arc welding parameters, and general procedure in optimizing machining operations sequence

#### **Text Books:**

- 1. Optimal design Jasbir Arora, Mc Graw Hill (International) Publishers
- 2. Optimization for Engineering Design Kalyanmoy Deb, PHI Publishers
- 3. Engineering Optimization S.S.Rao, New Age Publishers

#### **Reference Books:**

- 1.Genetic algorithms in Search, Optimization, and Machine learning D.E.Goldberg, Addison-Wesley Publishers
- 2. Genetic Programming- Koza
- 3. Multi objective Genetic algorithms Kalyanmoy Deb, PHI Publishers



#### M.TECH. IN CAD/CAM COURSE STRUCTURE & SYLLABI

<b>Course Code</b>	ourse Code INDUSTRIAL ROBOTICS & EXPERT SYSTEMS			P	С				
21D04202	INDUSTRIAL RODOTICS & EXTERT STSTEMS	$\frac{\mathbf{L}}{3}$	T 0	0	3				
21004202	Semester	II	U	U	13				
Schiester   11									
Course Objectives:									
• To teach students the basics of robotics, construction features, sensor applications, robot cell design, robot programming and application of artificial intelligence and expert systems in robotics.									
Course Outcom	Course Outcomes (CO): Student will be able to								
	to the basics kinematics of robotics, and are able to understand the ficial intelligence and expert systems in robotics	he ro	obot j	progr	amming				
UNIT - I	INTRODUCTION AND ROBOT KINEMATICS	Lec	cture	Hrs:0	)9				
End effectors –	and scope of Industrial robots – Robot anatomy – Work volume – Sensors. Robot Kinematics – Direct and inverse kinematics – Robot lators – Robot dynamics – Methods for orientation and location of o	t traj	jector						
UNIT - II	ROBOT DRIVES AND CONTROL	Lec	cture	Hrs:	09				
Controlling the Robot motion – Position and velocity sensing devices – Design of drive systems – Hydraulic and Pneumatic drives – Linear and rotary actuators and control valves – Electro hydraulic servo valves, electric drives – Motors – Designing of end effectors – Vacuum, magnetic and air operated grippers.									
UNIT - III	ROBOT SENSORS	Lec	cture	Hrs:	09				
Transducers and Sensors – Tactile sensor – Proximity and range sensors – Sensing joint forces – Robotic vision system – Image Representation - Image Grabbing –Image processing and analysis – Edge Enhancement – Contrast Stretching – Band Rationing - Image segmentation – Pattern recognition – Training of vision system.									
UNIT - IV	ROBOT CELL DESIGN AND APPLICATION	Leo	cture	Hrs:	09				
machine interfer	Robot work cell design and control – Safety in Robotics – Robot cell layouts – Multiple Robots and machine interference – Robot cycle time analysis. Industrial application of robots.								
UNIT - V	ROBOT PROGRAMMING, ARTIFICIAL INTELLIGENCE AND EXPERT SYSTEMS	Leo	cture	Hrs:	09				
Methods of Robot Programming – Characteristics of task level languages lead through programming methods – Motion interpolation. Artificial intelligence – Basics – Goals of artificial intelligence – AI techniques – problem representation in AI – Problem reduction and solution techniques - Application of AI and KBES in Robots.									
Text Books:									

#### **Text Books:**

1. K.S. Fu, R.C. Gonzalez and C.S.G. Lee, "Robotics Control, Sensing, Vision and Intelligence", Mc Graw Hill, 1987



#### M.TECH. IN CAD/CAM COURSE STRUCTURE & SYLLABI

2. Yoram Koren," Robotics for Engineers' Mc Graw-Hill, 1987

#### **Reference Books:**

- 1. Kozyrey, Yu. "Industrial Robots", MIR Publishers Moscow, 1985.
- 2. Richard. D, Klafter, Thomas, A, Chmielewski, Michael Negin, "Robotics Engineering An Integrated Approach", Prentice-Hall of India Pvt. Ltd., 1984.
- 3. Deb, S.R." Robotics Technology and Flexible Automation", Tata Mc Graw-Hill, 1994.
- 4. Mikell, P. Groover, Mitchell Weis, Roger, N. Nagel, Nicholas G. Odrey," Industrial Robotics Technology, Programming and Applications", Mc Graw-Hill, Int. 1986.
- 5. Timothy Jordanides et al ,"Expert Systems and Robotics ", Springer –Verlag, New York, May 1991.

- https://freevideolectures.com/course/4560/nptel-mechanism-robot-kinematics
- https://see.stanford.edu/course/cs223a
- https://cosmolearning.org/courses/introduction-to-robotics/video-lectures/
- https://www.youtube.com/watch?v=0yD3uBshJB0
- https://nptel.ac.in/courses/112/105/112105236/
- https://www.youtube.com/watch?v=xrwz9IxpMJg
- https://www.coursehero.com/file/59785981/Lecture-9-Robot-cell-designppt/
- https://www.plantautomation-technology.com/articles/different-types-of-robot-programming-languages



#### M.TECH. IN CAD/CAM COURSE STRUCTURE & SYLLABI

Course Code	CNC TECHNOLOGY & PROGRAMMING	L	T	P	C
21D04203a	Program Elective Course - III	3	0	0	3
Semester		II			

Course Objectives: Student will be able to study

- Safety in the CNC environment
- CNC Machine Tools compared to Manual Machine tools
- Repeatability and Speed is the Key to CNC C. Programming
- Manual Programming
- CAD/CAM Programming CNC Lathe 1. Uses 2. Setups 3. Tooling 4. CNC Lathe Project
- CNC Mill a. Uses b. Setups c. Tooling d. CNC Mill Project Course Topic

Course Outcomes (CO): Student will be able to

Upon completion of this course, the student will be able to:

- Understand the basic procedures and concepts of programming, set up and operation of a
- CNC Machining Centre.
- Identify and understand the basic programming codes.
- Create geometry and tool paths from the specifications on a blueprint for simple parts using
- Master cam programming software.
- Identify and define the functions of the CNC machine control.
- Set up the CNC machining center for manufacturing simple parts
- Manufacture simple parts on the CNC machining center.

### UNIT - I Introduction to CNC Machine tools Lecture Hrs: 09

Evolution of Computerized control in manufacturing, Components, Working principle of CNC, DNC and Machining centers.

Constructional features of CNC machine tools: Introduction, Spindle drives, Transmission belting, axes feed drives, Slide ways, Ball screws.

Accessories: Work tables, Spindles, Spindle heads, Beds and Columns, Tooling – Automatic Tool changer (ATC).

UNIT - II	Feedback devices	Lecture Hrs: 09

Introduction, Digital incremental displacement measuring systems, Incremental rotary encoders, Moire fringes, Digital absolute measuring system.

Electro-magnetic analogue position transducers: Principle, advantages, characterstics, Synchros, Synchro-Resolvers, Inductos, Laser interferometer.

	UNIT - III	Control Systems and interface	Lecture Hrs: 09
ı			

Open and closed loop systems, Micro processor based CNC systems, block diagram of typical CNC system, description of hard ware and soft interpolation systems, Standard and optional features of CNC control systems.



#### M.TECH. IN CAD/CAM COURSE STRUCTURE & SYLLABI

#### UNIT - IV APT programming

Lecture Hrs: 09

APT language structure, APT geometry, Definition of point, time, vector, circle, plane, patterns and matrices. APT motion commands: setup commands, point-to point motion commands, continuous path motion commands, post processor commands, control commands, Macro subroutines, Part programming preparation for typical examples.

#### UNIT - V Economics and Maintenance of CNC machine tools

Lecture Hrs: 09

Introduction, factors influencing selection of CNC machines, Cost of operation of CNC machines, Maintenance features of CNC machines, Preventive maintenance, Documentation, Spare parts, Training in Maintenance.

#### **Text Books:**

- 1. Computer Numerical Control Machines Dr. Radha Krishnanan, New Central Book Agency
- 2. Computer Numerical Control Machines Hans B. Keif and T. Frederick Waters Macmillan/McGraw Hill.

#### **Reference Books:**

- 1.CNC Machines B.S. Aditahn and Pabla
- 2. CNC Machining technology Springer Verlag
- 3. Computer Numerical Machine tools G.E. Thyer, NEWNES

- https://nptel.ac.in/courses/112/105/112105211/
- https://academy.titansofcnc.com/files/Fundamentals\_of\_CNC\_Machining.pdf http://home.iitk.ac.in/~nsinha/CNC.pdf
- https://www.thomasnet.com/articles/custom-manufacturing-fabricating/understanding-cnc-machining/
- https://www.hubs.com/knowledge-base/cnc-machining-manufacturing-technology-explained/
- https://www.youtube.com/watch?v=P0BvBbQoiok
- https://www.youtube.com/watch?v=bfTQVixviAo
- https://en.wikipedia.org/wiki/APT (programming language)

L T P C



Course Code

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#### M.TECH. IN CAD/CAM COURSE STRUCTURE & SYLLABI

COMPUTER GRAPHICS

Course Code	COMPUTER GRAPHICS	L	T	P	C	
21D04203b	Program Elective Course - III	3	0	0	3	
	Semester	II				
<u> </u>						
Course Objective	es:					
• The students	can understand the Basics of computer Graphics like drawing lin	e, ar	c etc.	, Dra	wing	
spline curves,	Creation of surfaces, Algorithms for 3D viewing, Available draw	ing s	tanda	ırds.		
Course Outcome	s (CO): Student will be able to understand					
Basics of com	puter Graphics like drawing line, arc etc.					
<ul> <li>Drawing of sp</li> </ul>	oline curves					
<ul> <li>Creation of su</li> </ul>	rfaces					
• Algorithms fo	or 3D viewing					
	wing standards					
	uputer Graphics like drawing line, arc etc.					
UNIT - I	Introduction to computer graphics	Lec	ture	Hrs:	09	
Color CRT raste	r scan monitors, plasma display & liquid crystal display mon	nitors	s, co	mput	er inpu	
devices, hard copy			,	•	•	
	phics: Line drawing algorithms – DDA & Bresenham algorith	ms,	circl	e gei	neratio	
	asterization, displaying lines, characters and polygons.	,		C		
UNIT - II	Filling algorithms	Lec	ture	Hrs:	09	
polygon filling, ed	lge fill algorithm, seed fill algorithm, fundamentals of antialiasing	and	half	tonin	g.	
UNIT - III	Line CLIPPING	Lec	cture	Hrs:	09	
01/22 222					<u> </u>	
	algorithm, Cohen-Sutherland subdivision line clipping algorithm,	mid	point	t sub	divisio	
algorithm.						
	; polygon clipping, reentrant polygon clipping – Sutherland –	Hod	lgema	an al	gorithn	
character clipping	, 3D- clipping.					
UNIT - IV	Transformations	Lec	ture	Hrs:	09	
Cartesian and hon	nogeneous coordinate systems two dimensional and three dimensi	onal	trans	sform	ations	
	Shearing, Zooming, viewing transformation, reflection, rot					
concatenation.	2.10m.1.1g,				•••	
UNIT - V	Rendering	Lec	ture	Hrs:	09	
Shading algorithm	wal algorithms, surface removal algorithms, painters, Warnock, Z-hms: Constant intensity algorithm, Phong's shading algorithms algorithms.					



#### M.TECH. IN CAD/CAM COURSE STRUCTURE & SYLLABI

#### **Text Books:**

- 1. Procedural elements for computer graphics-D.F.Rogers, Tata McGraw-Hill.
- 2. Computer Graphics-Donald Hearn & M.P. Bakers.

#### Reference Books:

1. Computer graphics-Harrington.

- https://lecturenotes.in/subject/59/computer-graphics-cg
- https://www.dgp.toronto.edu/~hertzman/418notes.pdf
- http://www2.cs.uidaho.edu/~jeffery/courses/324/lecture.html
- http://personal.ee.surrey.ac.uk/Personal/J.Collomosse/pubs/cm20219.pdf
- http://www.svecw.edu.in/Docs%5CCSECGLNotes2013.pdf
- https://www.youtube.com/watch?v=fwzYuhduME4
- https://nptel.ac.in/courses/106/103/106103224/
- https://nptel.ac.in/courses/106/102/106102065/



#### M.TECH. IN CAD/CAM COURSE STRUCTURE & SYLLABI

<b>Course Code</b>	GLOBAL INTEGRATED MANUFACTURING	L	T	P	C
21D04203c	Program Elective Course - III	3	0	0	3
	Semester	II			

#### Course Objectives: Student will be able to understand

- Globaly Emphasizes the integration of manufacturing enterprise using computer-
- integrated manufacturing (CIM) technologies.
- It employs CAD/CAM interface and
- other CIMsubsystems, database management, facility layout, Grouptechnology, teamwork, and manufacturing operations.

#### Course Outcomes (CO): Student will be able to

- Develop an understanding of computer-integrated manufacturing (CIM) and its impact on productivity, product cost, and quality.
- Obtain an overview of computer technologies including computers, database and data collection, networks, machine control, etc, as they apply to factory management and factory floor operations.
- Describe the integration of manufacturing activities into a complete system.

### UNIT - I INTRODUCTION Lecture Hrs: 09

Evolution of manufacturing, CAD/CAM and CIM – Globalization - Scope of CIM - Segments of generic CIM, computers and workstations, an overview of CIM software. World class manufacturing and its importance.

### UNIT - II GLOBAL MANUFACTURING ENTERPRISE Lecture Hrs: 09

Global manufacturing revolution – Reconfigurable machine – Reconfigurable manufacturing system - Production design for globalization – Location of manufacturing plants – Global business strategies – Global strategic alliance – IT-based enterprise – Information transfer in manufacturing systems - PRIDE – Competitive advantage: Logistics – Strategic sourcing - Supply chain - The dilemma of globalization – Where manufacturing enterprises heading?

### UNIT - III INTERNATIONAL LOGISTICS Lecture Hrs: 09

Introduction – supply chain background - outbound logistics functions – inbound logistics functions – overall logistics activities – logistics intermediates. Economic importance. Logistics media: ocean ships (cargo types), air transportation, surface transportation. Terms of sale and payment. Documentation and insurance: cargo, hull, air, land transport – settlement of insurance – claims. Famine relief logistics – demand forecasting – sourcing models – packaging – managing inventories - site/route selection – warehousing and storage.

INTERNAL SOURCING: Introduction – why sourcing is global? – design of global sourcing system – global sourcing and procurement – issues in import and export.

FUTURE ISSUES IN INTERMEDIATE LOGISTICS: Overview – increase use of world-class logistics practices – multi-country trade alliances – one stop shopping concept – amodalism – environmental concerns – space transportation and exploration – The internet.



#### M.TECH. IN CAD/CAM COURSE STRUCTURE & SYLLABI

#### UNIT - IV CNC TECHNOLOGY AND ROBOTIC SYSTEMS Lecture Hrs: 09

Principles of numerical control, types of CNC machines, features of CNC systems, programming techniques, capabilities of a typical NC, CAM software, integration of CNC machines in CIM environment, DNC – FMS – objectives – components – FMS layout configurations – FMS classification – ERP. Material handling systems – basics and advanced: conveyor analysis, AGV analysis. Warehousing – storage and retrieval systems: AS/RS analysis. Overview of JIT. Robotic systems-types of robots and their performance capabilities, programming of robots, hardware of robots, kinematics of robots, product design for robotized manufacturing, applications of robots in manufacturing and assembly. Process planning, variant and generative process planning methods – manual vs CAPP - AI in process planning.

### UNIT - V MANUFACTURING SYSTEM SOFTWARE Lecture Hrs: 09

CIM architecture - Production management system (PMS) - forecasting, master production schedule, MRP, capacity planning, shop floor control (SFC), factory data collection system (FDS) - Automatic data capture (ADC) method and its techniques - Bar code - types of bar codes - Data acquisition system - inventory management, product routing, job costing, marketing applications - Applications of ADC - Basics of networking concepts, networking devices.

VIRTUAL ORGANISATION: Paperless factory – Mobile office - Introduction of virtual reality and application - Virtual prototyping – Virtual manufacturing - Virtual instrumentation and measurement - Virtual enterprises.

#### **Text Books:**

- 1. Donal F Wood, Anthony P Barone, Paul R Murthy and Daniel L Wardlow, "International logistics", AMACOM. 2007.
- 2. Voram Koren, "The Global Manufacturing Revolution: Product Process Business Integration and Reconfigurable Systems", Kindle Edition, 2011.
- 3. Mikell P Groover, "Automation of Production Systems and Computer Integrated Manufacturing", Pearson Education, New Delhi, 2001.

#### **Reference Books:**

- 1. Lee Kunwoo, "CAD/CAM/CAE Systems", Addition, Wesley, USA, 1999.
- 2. Kant Vajpayee S, "Principles of Computer Integrated Manufacturing", Prentice Hall, India, New Jersey, 2003.
- 3. Radha krishnan P, Subramanyan S and Raju V, "CAD/CAM/CIM", New Age International Pvt. Ltd, New Delhi,

- https://nptel.ac.in/courses/112/104/112104289/
- https://nptel.ac.in/courses/112/105/112105249/
- https://www.youtube.com/watch?v=lRm9GiGoZKg
- https://osme.co.in/wp-content/uploads/2020/05/6TH-SEM-MECHANICAL-ENGG-Advance-manufacturing-and-CAD-CAM.pdf
- https://www.cet.edu.in/noticefiles/259\_Lecturer%20Note%20on%20Mechatronics-ilovepdf-compressed.pdf



#### M.TECH. IN CAD/CAM COURSE STRUCTURE & SYLLABI

21D04204a  Course Objectives: Stude  Understand architecture	are of the mechatronics system design and charac		T 0	P 0	<u>C</u> 3									
Course Objectives: Stude  • Understand architectur	ent will be able to  are of the mechatronics system design and character mechatronic systems.  pts of microprocessor, microcontroller and PLC u	II teristics			3									
Understand architectur	ent will be able to  are of the mechatronics system design and charac  mechatronic systems.  pts of microprocessor, microcontroller and PLC u	teristics	of senso											
Understand architectur	are of the mechatronics system design and character mechatronic systems.  pts of microprocessor, microcontroller and PLC u		of senso											
Understand architectur	are of the mechatronics system design and character mechatronic systems.  pts of microprocessor, microcontroller and PLC u		of senso											
	mechatronic systems.  pts of microprocessor, microcontroller and PLC u		of senso		Course Objectives: Student will be able to									
and their selection for	pts of microprocessor, microcontroller and PLC u	sed in m		• Understand architecture of the mechatronics system design and characteristics of sensors and actuators										
		sed in m		and their selection for mechatronic systems.										
• Learn the basic concer			echatron	ics syste	em.									
	· · · · · · · · · · · · · · · · · · ·			•										
	At the end of the course the students shall be able		8											
Y . C 1														
	ctuator for a mechatronic system.													
	and develop a mechatronic system.													
Design and develop M	MEMS for various industrial applications.													
UNIT - I	INTRODUCTION	Lecture	Hrs: 09	ı										
Introduction to Mechatro	onics - Systems - Mechatronics in Products - N	/leasuren	nent Sys	stems - (	Control									
	ign and Mechatronics Design.	2000		,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,	00111101									
UNIT - II	SENSORS AND TRANSDUCERS	Lecture	Hrs:09											
Introduction - Performanc	ce Terminology - Displacement, Position and Pro	oximity -	- Velocit	ty and M	Iotion -									
Fluid pressure - Tempera systems.	ture sensors - Light sensors - Selection of sensors	ors – Sig	gnal pro	cessing -	- Servo									
UNIT - III	MICROPROCESSORS IN	Lecture	Hrs: 09	1										
	MECHATRONICS													
	re - Pin configuration - Instruction set - Program													
	acing input and output devices - Interfacing D/A			/D conv	erters –									
Applications - Temperatur	re control - Stepper motor control - Traffic light c	ontroller	-											
UNIT - IV	PROGRAMMABLE LOGIC	Lecture	Hrs: 09	1										
	CONTROLLERS													
Introduction - Basic struc	cture - Input / Output processing - Programmin	g -Mner	nonics	Timers.	Internal									
	handling - Analog input / output - Selection of P			,										
UNIT - V	DESIGN AND MECHATRONICS	Lecture	Hrs: 09	1										
Designing - Possible desig	gn solutions - Case studies of Mechatronics syster	ns.												
Text Books:														

1. Michael B.Histand and David G. Alciatore, "Introduction to Mechatronics and

Measurement Systems", McGraw-Hill International Editions, 1999.



#### M.TECH. IN CAD/CAM COURSE STRUCTURE & SYLLABI

- 2. Bradley, D.A., Dawson, D, Buru, N.C. and Loader, AJ, "Mechatronics", Chapman and Hall, 1993.
- 3. Ramesh.S, Gaonkar, "Microprocessor Architecture, Programming and Applications" Wiley Eastern, 1998.

#### **Reference Books:**

- 1.Lawrence J.Kamm, "Understanding Electro-Mechanical Engineering, An Introduction to Mechatronics", Prentice-Hall, 2000.
- 2. Ghosh, P.K. and Sridhar, P.R., 0000 to 8085, "Introduction to Microprocessors for Engineers and Scientists", Second Edition, Prentice Hall, 1995.

- https://www.cet.edu.in/noticefiles/259\_Lecturer%20Note%20on%20Mechatronics-ilovepdf-compressed.pdf
- https://lecturenotes.in/subject/137/mechatronics-mech
- http://engineering.nyu.edu/mechatronics/Control\_Lab/Criag/Craig\_RPI/2001/Mechatronics%20Lect ure%20Notes.htm
- https://jcboseust.ac.in/mechanical/images/mtech1stsem/mechatronics\_product\_design.pdf
- https://www.youtube.com/watch?v=tAkkUNEknGk
- https://nptel.ac.in/courses/112/107/112107298/
- https://www.youtube.com/watch?v=ncSnIkBO-X0



Course Code	RAPID PROTOTYPING	L	Т	P	С
21D04204b	Program Elective Course - IV	3	0	0	3
	Semester	II	,	•	'
Course Objective	es:				
• At the end of	f this course the students would have developed a thoroug	h un	derst	anding	of the
principle meth	nods, areas of usage, possibilities and limitations as well as env	ironn	nental	effec	ts of the
•	ping Technologies.				
Course Outcome	s (CO): Student will be able to				
• It halps the st	and onto to got familiarized with the various methods of rapid	rotot	inc	, toobs	nologias
-	rudents to get familiarized with the various methods of rapid p	protoi	yping	, tecili	lologies
and rapid tool	ing.				
UNIT - I	Introduction	Lec	ture I	Hrs:09	
	inti oddetion	Lec	tuic i	115.07	
Need for the com	pression in product development, History of RP system, Survey	of a	oplica	tions.	Growth
	d classification of RP system.			,	
	ohy System: Principle, Process parameter, Process details, Dat	a pre	parati	on, D	ata files
and machine detai		•	•		
	, 11				
UNIT - II	Fusion Decomposition Modeling	Lec	ture I	Irs:09	
Principle process	parameter, Path generation, Applications.				
	<b>ing:</b> Principle of operation, Machine details, Applications,				
		т	, T	T 00	
UNIT - III	Laminated Object Manufacturing	Lec	ture i	Irs:09	
Principle of Opera	ation, LOM materials, Process details, Applications.				
	ers: Principle, Thermal jet printer, Sander's model market,	3-D 1	orinte	, Gen	isys Xs
<del>-</del>	5, Object Quadra system.	•			•
UNIT - IV	LASER ENGINEERING NET SHAPING (LENS)	Lec	ture I	Irs:09	
	Indirect Rapid tooling- Silicon rubber tooling- Aluminum fill	-			
O.	st kriksite, 3Q keltool, etc, Direct Rapid Tooling Direct. Al		-		
11 1	e, Rapid Tool, DMILS, Prometal, Sand casting tooling, Lamin	ate to	oling	soft,	Tooling
vs. hard tooling.					
Coffmons for DD	STI files Overview of Solid view masies imies masie sem	mı:	ootic:	a oto	Intornat
	STL files, Overview of Solid view, magics, imics, magic com	mum	canol	ı, etc.	memet
based software, C	ollaboration tools.				
UNIT - V	Rapid Manufacturing Process Optimization	Lec	ture I	Hrs:	
				•	
Factors influencing	g accuracy, Data preparation error, Part building error, Error i	n fin	ishing	, Influ	ence of



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build orientation.

#### **Text Books:**

- 1." stereo lithography and other RP & M Technologies", Paul F.Jacobs, SME, NY 1996
- 2. "Rapid Manufacturing", Flham D.T & Dinjoy S.S, Verlog London 2001

#### **Reference Books:**

1. Rapid automated", Lament wood, Indus Press New York.

### **Online Learning Resources:**

- https://www.hubs.com/knowledge-base/introduction-fdm-3d-printing/
- https://slideplayer.com/slide/6927137/
- https://www.mdpi.com/2073-4360/12/6/1334
- https://www.centropiaggio.unipi.it/sites/default/files/course/material/2013-11-29%20-%20FDM.pdf
- https://lecturenotes.in/subject/197
- https://www.cet.edu.in/noticefiles/258\_Lecture%20Notes%20on%20RP-ilovepdf-compressed.pdf
- https://www.vssut.ac.in/lecture\_notes/lecture1517967201.pdf
- https://www.youtube.com/watch?v=NkC8TNts4B4



UNIT - IV

## JAWAHARLAL NEHRU TECHNOLOGICAL UNIVERSITY ANANTAPUR (Established by Govt. of A.P., ACT No.30 of 2008) ANANTHAPURAMU – 515 002 (A.P) INDIA

## M.TECH. IN CAD/CAM COURSE STRUCTURE & SYLLABI

Course Code	ARTI	FICIAL INTELLIGENCE & EXPERT	L	T	P	C
21D04204c		SYSTEMS (PE-IV)	3	0	0	3
		Semester	II			
<b>Course Objectives:</b>	•					
		ade to study the concepts of Artificial Intelli	gence. 1	.Learn the	method	s of
solving problem	ns using A	Artificial Intelligence.				
		of Expert Systems and machine learning.				
<b>Course Outcomes</b> (	(CO): St	udent will be able to				
• •		e amenable to solution by AI methods.				
* * *		nethods to solve a given problem.				
		m in the language/framework of different A	I method	ls.		ļ
• Implement basic	_					
		empirical evaluation of different algorithm	is on a p	roblem fo	ormalisati	ion,
and state the cor	nclusions	that the evaluation supports.	T -	** 00		
UNIT - I		Artificial Intelligence	Lecture	e Hrs:09		
representation, defin strategies –Introduct <b>Uniformed or pre</b> l Informed Search, On	ining a ption, preleliminary or Graphs	derlying assumption, Important of Al, Al problem, production systems and its char iminary concepts, examples of Search, problems, Concept: Examples of search problems, Heuristic Search techniques- Generate and constraint satisfaction, Means- Ends Analysis	acteristicolems. Uniforn Test, H	e, search med or B	and con	rch,
UNIT - II		<b>Knowledge Representation Issues</b>	Lecture	e Hrs: 09		
Declarative, Logic reasoning and it logi Use of Predicate	progran ic. <b>Logic:</b> I positiona	ing, Approaches, Issues in Kr, Types on the comming, Forward Vs Backward reasoning Representing simple facts, Instance and is I logic, FOPL, and properties of Wffs, in.	, Match	ing, Non ionships,	monoto Syntax	onic and
UNIT - III		Statistical and Probabilistic Reasoning	Lecture	e Hrs: 09		
		uncertainly, Probability and Bayes theorem works, Dempster- Shafer Theory, Fuzzy Log		nty facto	rs and R	Rule

Introduction, Structure and uses, Representing and using domain knowledge, Expert System Shells. Pattern recognition, introduction, Recognition and classification process, learning classification patterns, recognizing and understanding speech.

Lecture Hrs: 09

**Expert Systems** 

Introduction to Knowledge Acquisition: Types of learning, General learning model, and



#### M.TECH. IN CAD/CAM COURSE STRUCTURE & SYLLABI

performance measures.		
UNIT - V	Typical Expert Systems	Lecture Hrs: 09

MYCIN, Variants of MYCIN, PROSPECTOR DENDRAL, PRUFF etc.

Introduction to Machine Learning: Perceptons, Checker Playing examples,

Learning, Automata, Genetic Algorithms, Intelligent Editors.

#### **Text Books:**

- 1. "Artificial Intelligence", Elaine Rich & Kevin Knight, M/H 1983
- **2.** "Artificial Intelligence in Business", Wendry B.Ranch, Science & Industry –Vol -II application, Ph 1985.
- 3. "A Guide to Expert System" Waterman, D.A., Addison, Wesley inc. 1986.

#### **Reference Books:**

- 1. "Building expert system" Hayes, Roth, Waterman, D.A (ed), AW 1983.
- 2. "Designing Expert System", S.M. and Kulliknowske Weis, London Champion Hull 1984.

## **Online Learning Resources:**

- https://www.youtube.com/watch?v=11nzrNkn9D8
- https://www.youtube.com/watch?v=BXHcPESoaPY
- https://silo.tips/download/module-9-lecture-notes-5-expert-systems
- https://www.tutorialspoint.com/artificial\_intelligence/artificial\_intelligence\_expert\_systems.
   htm
- https://epub.uni-regensburg.de/13629/1/ubr06078\_ocr.pdf
- https://lecturenotes.in/subject/879/artificial-intelligence-and-expert-system
- https://www.vssut.ac.in/lecture\_notes/lecture1530018613.pdf
- https://www.cet.edu.in/noticefiles/271\_AI%20Lect%20Notes.pdf



#### M.TECH. IN CAD/CAM COURSE STRUCTURE & SYLLABI

<b>Course Code</b>	PROCESS AUTOMATION LABORATORY	L	T	P	C
21D04205		3	0	0	3
	Semester	II			

Course Objectives: Student will be able to

To review and train in CAD modeling.

To train on various areas of finite element analysis of mechanical components.

CAM lab

To train on part programming and program generation from a CAD model.

To train on machining in various CNC machines.

To train on various modern measuring instruments.

Course Outcomes (CO): Student will be able to

Students will be able to review and train in CAD modeling.

Students will be get trained on various areas of finite element analysis of mechanical components.

Students would get trained on part programming and program generation from a CAD model.

Students would get trained on machining in various CNC machines, Students would get trained on various modern measuring instruments.

#### List of Experiments:

- 1. Aristo XT Six axis Robot
  - a. Introduction to Robot programming
  - b. Robot programming exercises (Point-to-Point and continuous path task)
- 2. Either Online / Offline mode.
  - a. Simulation of a manufacturing system for increasing production rate.
  - b. Simulation of a simple automation system.
- 3. Either Online / Offline mode.
  - I. Hydraulic Circuits
  - a. Introduction to Automation studio & its control
  - b. Draw & Simulate the Hydraulic circuit for series & parallel cylinders connection
  - c. Draw & Simulate Meter-in, Meter-out and hydraulic press and clamping.
  - d. Sequencing circuits in hydraulics.
  - e. Synchronizing circuits in hydraulics.
  - II. Pneumatic circuits
    - a. Sequencing circuits in Pneumatics.
    - b. Synchronizing circuits in Pneumatics.
    - c. Design and Simulation of simple pneumatic circuit by using Cascade Method.
  - d. Design and Simulation of simple pneumatic circuit by using step counter method
- 4. Additive manufacturing machine
  - a. Introduction to Additive manufacturing Machine.
  - b. Design and fabrication of simple symmetrical and unsymmetrical components

Text Books: Lab Manual



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Course Code	CAM LAB	L	T	P	С
21D04206		3	0	0	3
	Semester			II	

#### Course Objectives: Student will be able to

- To get practical knowledge on manual part programming of CNC lathe machine by using G codes and M codes.
- To get practical knowledge on manual part programming of CNC milling and drilling machine by using G• codes and M codes.
- To get the practical knowledge on APT language.

#### **Course Outcomes (CO):**

- Upon successful completion students should be able to:
- Use an understanding of General and Machine (G& M) code to generate or edit a program which will operate a CNC Lathe.
- Apply mathematical methods to calculate Cartesian coordinates

## List of Experiments:

- 1. Manual part programming (using G and M codes) in CNC Lathe Machine
  - (a) Part programming for linear interpolation, circular interpolation, chamfering and grooving.
  - (b) Part programming by using standard canned cycles for facing, turning, taper turning and thread cutting.
- 2. Manual part programming (using G and M codes) in CNC Milling Machine
  - (a) Part programming for linear interpolation, circular interpolation and contour motions.
  - (b) Part programming involving canned cycles for drilling peak drilling and boring.
- 3. APT (Automatically Programmed Tools) language in CNC Milling and Lathe machine.
- 4. Cutting tool path generation using any one simulation package for different machining operation

Text Books: Lab Manual



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<b>Course Code</b>	ADVANCED TOOL DESIGN	L T P C						
21D04301a	Program Elective Course - V	3	0	0	3			
	Semester		Ι	II				
Course Objective								
	his course is to make the students to get familiarized wi	th the des	ign of va	rious too	ls that			
can be implemen	ted for different mechanical operations.							
<b>Course Outcom</b>								
It helps the stude	nts to get familiarized with advanced tool design for va	rious me	chanical o	operation	s which			
includes cutting,	jigs and fixtures, press tool dies and modern CNC mac	hine tools	S.					
UNIT - I	INTRODUCTION TO TOOL DESIGN	Lecture	Hrs: 09					
	ol Engineering – Tool Classifications– Tool Design Ob			esign in				
	Challenges and requirements- Standards in tool design-				sh – Fits			
	Tooling Materials- Ferrous and Non ferrous Tooling M							
	netallic tool materials-Designing with relation to heat tr							
UNIT - II	DESIGN OF CUTTING TOOLS	Lecture	Hrs: 09					
	etal cutting –Oblique and orthogonal cutting- Chip forn							
	ls – Milling cutters – Hole making cutting tools- Broach		s - Desig	n of Forn	a			
	file relieved cutters-Design of gear and thread milling c							
UNIT - III	DESIGN OF JIGS AND FIXTURES	Lecture						
	xed Gages - Gage Tolerances -selection of material fo							
	- Principles of location - Locating methods and device							
	ation in drilling – General considerations in the design of							
	truction – Thrust and Turning Moments in drilling - Dri							
	s – Vise Fixtures – Milling Fixtures – Boring Fixtures –		ng Fixtur	es – Lath	ıe			
	ing Fixtures – Modular Fixtures – Cutting Force Calcul		II 00					
UNIT - IV	DESIGN OF PRESS TOOL DIES	Lecture		1 D	• •			
	Method of Die operation—Clearance and cutting force ca							
	ts – Strippers and pressure pads- Presswork materials –		out – Sno	rt-run too	oning for			
UNIT - V	ng dies – Forming dies – Drawing dies-Design and dra: TOOL DESIGN FOR CNC MACHINE	Lecture	Har OO					
UNII - V	TOOLS	Lecture	П18. 09					
Introduction -To	poling requirements for Numerical control systems – Fix	ture desi	an for CN	VC mach	ine			
	and tombstone fixtures-Universal fixtures—Cutting tool			ve maem	inc			
	natic tool changers and tool positioners – Tool presetting			ation of t	he			
Brown and Sharp		o comer	ar onplan					
Text Books:								
	Community Color V.C. Conta WT of Decision, Test	M.C.	II:11 D1	1. 1 .				

- 1. Cyrll Donaldson, George H.LeCain, V.C. Goold, "Tool Design", Tata McGraw Hill Publishing Company Ltd., 2000.
- 2. E.G.Hoffman," Jig and Fixture Design", Thomson Asia Pvt Ltd, Singapore, 2004.

#### **Reference Books:**

- 1. Prakash Hiralal Joshi, "Tooling data", Wheeler Publishing, 2000
- 2. Venkataraman K., "Design of Jigs, Fixtures and Presstools", TMH, 2005



## M.TECH. IN CAD/CAM COURSE STRUCTURE & SYLLABI

## 3. Haslehurst M., "Manufacturing Technology", The ELBS, 1978.

#### Online Learning Resources:

https://www.iare.ac.in/sites/default/files/lecture\_notes/TOOL%20DESIGN\_Lecture\_Notes.pdf

https://www.cet.edu.in/noticefiles/261\_MMP%20Lecture%20Notes-ilovepdf-compressed.pdf

https://www.vssut.ac.in/lecture-notes.php?url=production-engineering

https://nptel.ac.in/courses/112/105/112105233/

https://www.youtube.com/watch?v=7MkX-sW97rI

https://nptel.ac.in/courses/112/105/112105126/#

https://youtu.be/7yzvno4AvKw



Course Code	DESIGN 1	FOR MANUFACTURING	L	T	P	C		
21D04301b	Progra	am Elective Course - V	3	0	0	3		
		Semester	III					
Course Objective	: Student will be abl	le to						
<ul> <li>Internalize the attributes along which the success or failure of a manufacturing process, machine, or system will be measured: quality, cost, rate and flexibility.</li> <li>Provide exposure to a range of current industrial processes and practices used to manufacture products in high and low volumes. Focus in depth on a few selectedprocesses.</li> <li>Understand the factors that control the rate of production and influence the quality, cost and flexibility of processes.</li> <li>Understand the impact of manufacturing constraints on product design and processplanning.</li> <li>Apply an understanding of variation to the factors that control the production rate and influence the quality, cost and flexibility of processes and systems.</li> </ul>								
	(CO): Student will							
product that is the tools and o	responsive to the cu	human need and create wealth. The stomer with high quality and low cos a manufacturing enterprise that is usin , and yet be able to make intelligent de	t. A gra g an un	aduate s familia	should ha	ave		
UNIT - I			Lecti	ure Hrs	:09			
basic principles of Materials: Selection	designing for econor n of materials for de	s in design process-general design rumical production-creativity in design. esign-developments in material technology with process selection-process se	ology-c	riteria	for mater			
UNIT - II			Lecti	ure Hrs	: 09			
dimensional toler	Machining processes: Overview of various machining processes-general design rules for machining-dimensional tolerance and surface roughness-Design for machining – ease – redesigning of components for machining ease with suitable examples. General design recommendations for machined parts.							
UNIT - III			Lecti	ure Hrs	: 09			
Metal casting: Appraisal of various casting processes, selection of casting process,-general design considerations for casting-casting tolerance-use of solidification, simulation in casting design- product design rules for sand casting.								
UNIT - IV			Lecti	ure Hrs	: 09			



#### M.TECH. IN CAD/CAM COURSE STRUCTURE & SYLLABI

**Metal joining:** Appraisal of various welding processes, factors in design of weldments – general design guidelines-pre and post treatment of welds-effects of thermal stresses in weld joints-design of brazed joints.

Forging: Design factors for forging – closed die forging design – parting lines of dies – drop forging die design – general design recommendations.

UNIT - V Lecture Hrs: 09

**Extrusion & Sheet metal work:** Design guide lines extruded sections-design principles for punching, blanking, bending, deep drawing-Keeler Goodman forging line diagram – component design for blanking.

**Plastics:** Visco elastic and creep behavior in plastics-design guidelines for plastic components- design considerations for injection moulding

#### **Textbooks:**

- 1. Design for manufacture, John cobert, Adisson Wesley. 1995
- 2. Design for Manufacture by Boothroyd,

#### **Reference Books**

1. ASM Hand book Vol.20

#### **Online Learning Resources:**

- https://nptel.ac.in/courses/112/101/112101005/
- https://www.iare.ac.in/sites/default/files/lecture\_notes/DFMA\_LECTURE\_NOTES.pdf
- https://ocw.mit.edu/courses/mechanical-engineering/2-008-design-and-manufacturing-ii-spring-2004/lecture-notes/
- https://dokumen.tips/documents/design-for-manufacturing-and-assembly-1-lecture-notes-on-design-for-manufacturing.html
- https://www.youtube.com/watch?v=ofmbhbVCUqI
- https://onlinecourses.nptel.ac.in/noc21\_me66/preview



Course Code	COM	PUTER AIDED TOOLS FOR MANUFACTUR	RING	L	T	P	C	
21D04301c		Program Elective Course - V		3	0	0	3	
		Sen	nester		<u>I</u> ]	II		
Course Objectives:								
tools that can	be imple	course is to make the students to get familiarized emented in various industrial applications.	with va	arious	comp	outer	aided	
Course Outcome	es (CO):	Student will be able to						
• It helps the students to get familiarized with computer aided tools for various industrial applications which includes manufacturing, process planning, inspection, data management and reverse engineering.								
UNIT - I		COMPUTER AIDED MANUFACTURING	Lectu	re Hrs:	09			
Integrating CAD, CNC and DNC –	NC and	<ul> <li>Removing, Forming, Deforming and joining</li> <li>CAM – Machine tools – Point to point and corgramming – Basics, Languages, G Code, M Code</li> <li>AM NC Programming – Production Control – Cel</li> </ul>	tinuous , APT -	path 1 - Tool	mach path	ining gene	g, NC,	
UNIT - II		COMPUTER AIDED PROCESS PLANNING	Lectur	re Hrs:	09			
Benefits, Model a	and Arcl	in CAD/CAM Integration – Computer Aided Producture – CAPP Approaches – Variant, Generati-I, D-CLASS and CMPP – Criteria in selecting a C	ve and	Hybrid	– Dev 1 – P	velop roces	ment, ss and	
UNIT - III		COMPUTER AIDED INSPECTION	Lectu	re Hrs:	09			
Tolerance Accum Drafting and man	nulation nufactur	<ul> <li>Need for Tolerances – Conventional Tolerar</li> <li>and Surface quality – Geometric Tolerances – Tolerance</li> <li>ing – Tolerance Analysis – Tolerance synthesis</li> <li>on Methods – Non Contact Inspection Methods – Inspection Methods</li></ul>	olerance – Cor	es Prac mputer	ctices	in d	esign,	
UNIT - IV		REVERSE ENGINEERING	Lectu	re Hrs:	09			
Scope and tasks of Reverse Engineering – Domain Analysis – Process Duplicating – Tools for RE – Developing Technical data – Digitizing techniques – Construction of surface model – Solid part model – Characteristic evaluation – Software's and its application – CMM and its feature capturing – surface and solid modeling.								
UNIT - V		DATA MANAGEMENT	Lectu	re Hrs:	09			
Strategies for Reverse Engineering Data management – Software application – Finding renewable software components – Recycling real time embedded software – Design experiments to evaluate a RE tools – Rule based detection for RE user interface – RE of assembly programs.								



#### M.TECH. IN CAD/CAM COURSE STRUCTURE & SYLLABI

#### **Text Books:**

- 1. Ibrahim Zeid and R. Sivasubramanian, "CAD/CAM Theory and Practice", Revised First special Indian Edition, Tata Mc Graw Hill Publication, 2007
- 2. Catherine A. Ingle, "Reverse Engineering", Tata Mc Graw Hill Publication, 1994
- 3. Ibrahim Zeid, "Mastering CAD/CAM", special Indian Edition, Tata Mc Graw Hill Publication, 2007.

#### **Reference Books:**

- 1. David D. Bedworth, Mark R. Henderson, Philp M. Wolfe, "Computer Integrated Design and manufacturing", Mc Graw Hill International series, 1991
- 2. Linda Wills, "Reverse Engineering" Kluwer Academic Press, 1996
- 3. Donald R. Honra, "Co-ordinate measurement and reverse Engineering, American Gear Manufacturers Association.

## **Online Learning Resources:**

- https://www.autodesk.com/products/fusion-360/blog/computer-aided-manufacturing-beginners/
- https://www.youtube.com/watch?v=EgKc9L7cbKc
- https://nptel.ac.in/courses/112/105/112105211/
- https://lecturenotes.in/subject/409/computer-aided-design-and-manufacturing-cadm
- https://www.youtube.com/watch?v=9dd3M2a4LKI
- https://www.iare.ac.in/sites/default/files/lecture\_notes/CAD\_CAM\_LECTURE%20NOTES.pdf
- https://learnmech.com/computer-aided-inspection-cim-notes/
- https://canvas.instructure.com/courses/838884/pages/unit-3-lesson-6-reverse-engineering



M.TECH. IN CAD/CAM COURSE STRUCTURE & SYLLABI

# AUDIT COURSE-I



Course Code	ENGLISH FOR RESEARCH PAPER WRITING	L	T	P	C
21DAC101a		2	0	0	0
	Semester			I	
Course Objectiv	res: This course will enable students:				
Understa	nd the essentials of writing skills and their level of readability				
<ul> <li>Learn ab</li> </ul>	out what to write in each section				
• Ensure q	ualitative presentation with linguistic accuracy				
Course Outcom	es (CO): Student will be able to				
<ul> <li>Understa</li> </ul>	nd the significance of writing skills and the level of readability				
<ul> <li>Analyze</li> </ul>	and write title, abstract, different sections in research paper				
<ul> <li>Develop</li> </ul>	the skills needed while writing a research paper				
UNIT - I		ectur	e Hrs	s:10	
	Research Paper- Planning and Preparation- Word Order- Useful Ph				
	es-Structuring Paragraphs and Sentences-Being Concise and Remo	oving	Red	unda	ncy
-Avoiding Ambig					
UNIT - II			e Hrs		
	nents of a Research Paper- Abstracts- Building Hypothesis-Resea			em -	
Highlight Finding	gs- Hedging and Criticizing, Paraphrasing and Plagiarism, Cauteria	zatio	n		
UNIT - III			e Hrs		
	ew of the Literature – Methodology - Analysis of the Data-Finding	gs - D	)iscu	ssion	-
Conclusions-Rec	ommendations.				
UNIT - IV		Le	cture	Hrs:	9
	for writing a Title, Abstract, and Introduction				
UNIT - V				Hrs:	
	uage to formulate Methodology, incorporate Results, put forth Arg	ume	nts a	nd dr	aw
Conclusions					
Suggested Read					
	R (2006) Writing for Science, Yale University Press (available on	Goo	gle I	Books	;)
	urriculum of Engineering & Technology PG Courses [Volume-I]		4 P		
	2006) How to Write and Publish a Scientific Paper, Cambridge Unit			ess	
I	N (1998), Handbook of Writing for the Mathematical Sciences, S	IAW	•		
Highmar	i sbook Vallwork , English for Writing Research Papers, Springer New Yor	ılı Da	ordra	oht	
	rg London, 2011	K D(	лure	CIIL	



## M.TECH. IN CAD/CAM COURSE STRUCTURE & SYLLABI

	COURSE STRUCTURE & STELLABI				
Course Code	DISASTER MANAGEMENT	L	T	P	C
21DAC101b	DISASTER MANAGEMENT	2	0	0	0
	Semester			I	
Course Objectives:	This course will enable students:				
	monstrate critical understanding of key concepts in	n disas	ter risk	reducti	ion
	tarian response.				
_	valuatedisasterriskreduction and humanitarian response po	licy and	d praction	ce from	
<ul> <li>Multiple per</li> </ul>	*				
	nder standing of standards of humanitarian response and praction of the contraction of	calrelev	vanceins	specific	types
	and conflict situations				
	derst and the strengths and weaknesses of disaster management of the strengths and the strengths and the strengths and the strengths are strengths and the strengths and the strengths are strengths are strengths and the strengths are strengths are strengths and the strengths are strengths and the strengths are strengths				
1 5	ng in different countries, particularly their home country or	the co	untries	they wo	rk in
UNIT - I					
Introduction:					
Disaster:Definition,I	Factors and Significance; Difference Between Hazard and Disactors and	ster;Na	turalanc	1	
	Difference, Nature, Types and Magnitude.				
Disaster Prone Areas					
	ones; Areas Prone to Floods and Droughts, Landslides and				
_	al Hazards with Special Reference to Tsunami; Post-Disas	ter Dise	eases an	d Epide	mics
UNIT - II					
Repercussions of Di					
	Loss of Human and Animal Life, Destruction of Ecosyster				
	isms, Cyclones, Tsunamis, Floods, Droughts and Famines, Landers and Fa				
	Nuclear Reactor Meltdown, Industrial Accidents, Oil Slic	ks and	Spills, C	Outbreal	ks of
	ics, War and Conflicts.				
UNIT - III					
Disaster Preparednes					
Preparedness: Monit	toring of Phenomena Triggering ADisasteror Hazard; Eval	uation o	of Risk:	Applica	ation
	Data from Meteorological and Other Agencies, Media Re	eports: (	Governi	nental a	and
Community Prepare	dness.				
UNIT - IV					
Risk Assessment Dis					
	nts, Disaster Risk Reduction, Global and National Disaster				
TechniquesofRiskAs	ssessment,GlobalCo-OperationinRiskAssessmentand Warr	ning, Pe	ople's I	Participa	ation
in Risk Assessment.	Strategies for Survival.				
UNIT - V					
Disaster Mitigation:					

Meaning, Concept and Strategies of Disaster Mitigation, Emerging Trends In Mitigation. Structural

Mitigation and Non-Structural Mitigation, Programs of Disaster Mitigation in India.

#### **Suggested Reading**

- 1. R.Nishith, Singh AK, "Disaster Management in India: Perspectives, issues and strategies
- 2. "'New Royal book



## M.TECH. IN CAD/CAM COURSE STRUCTURE & SYLLABI

Company..Sahni,PardeepEt.Al.(Eds.),"DisasterMitigationExperiencesAndReflections",PrenticeHa ll OfIndia, New Delhi.

3. GoelS.L.,DisasterAdministrationAndManagementTextAndCaseStudies",Deep&Deep Publication Pvt. Ltd., New Delhi



## M.TECH. IN CAD/CAM COURSE STRUCTURE & SYLLABI

<b>Course Code</b>	SANSKI	RITFOR TECHNICAL KN	NOWLEDGE	L	T	P	C
21DAC101c				2	0	0	0
			Semester	I			
Course Objecti	ves: This cou	se will enable students:					
To get a	working knov	vledge in illustrious Sanskrit	, the scientific lang	uage i	n the wo	orld	
<ul> <li>Learning</li> </ul>	g of Sanskrit to	improve brain functioning					
<ul> <li>Learning</li> </ul>	gofSanskrittod	evelopthelogicinmathematic	s,science&othersul	bjects	enhancii	ng the	memory
power							
The eng	ineering schol	ars equipped with Sanskrit v	vill be able to explo	re the	huge		
Knowle	dge from ancie	entliterature					
<b>Course Outcon</b>	nes (CO): Stud	lent will be able to					
Underst	anding basic S	anskrit language					
<ul> <li>Ancient</li> </ul>	Sanskrit litera	ture about science &technol	ogy can be underst	ood			
		ge will help to develop logic	<b>-</b>				
UNIT - I							
Alphabets in Sar	nskrit,		·				
UNIT - II							
Past/Present/Fut	ure Tense, Sim	ple Sentences					
UNIT - III							
Order, Introduct	ion of roots						
UNIT - IV							
Technical inform	nation about Sa	anskrit Literature					
UNIT - V							
Technical conce	pts of Enginee	ring-Electrical, Mechanical,	Architecture, Math	ematic	:s		
Suggested Read							
		was, Sanskrit-Bharti Public					
		"Prathama Deeksha- Ve	mpatiKutumbshast	ri, Ras	shtriyaSa	anskrit	
Sansthanam, Ne	w Delhi Public	cation					

3."India's Glorious ScientificTradition" Suresh Soni, Ocean books (P) Ltd., New Delhi



M.TECH. IN CAD/CAM COURSE STRUCTURE & SYLLABI

# AUDIT COURSE-II



## M.TECH. IN CAD/CAM **COURSE STRUCTURE & SYLLABI**

<b>Course Code</b>		PEDAGOGY STUDIES	L	T	P	C
21DAC201a			2	0	0	0
		Semester	II			
Course Objecti	ves: This cou	rse will enable students:				
• Reviewe	existingeviden	ceonthereviewtopictoinformprogrammedesigna	ndpolic	y makir	ng under	rtaken
•	•	encies and researchers.				
<ul> <li>Identify</li> </ul>	critical evider	nce gaps to guide the development.				
<b>Course Outcon</b>	nes (CO): Stu	dent will be able to				
	s will be able t					
<ul> <li>Whatpe</li> </ul>	dagogicalpract	icesarebeingusedbyteachersinformalandinforma	alclassr	ooms in	develo	ping
countrie					,	
• What is	the evidence of	on the effectiveness of these pedagogical practic	es, in w	hat		
• condition	ons, and with w	hat population of learners?				
		ion(curriculumandpracticum)andtheschoolcurric	culumai	nd guida	ance ma	terials
	port effective	*		C		
UNIT - I						
Introduction and	l Methodology	: Aims and rationale, Policy back ground, Conce	eptual f	rame wo	ork and	
		ng, Curriculum, Teachereducation. Conceptual fram	nework	,Resear	ch quest	ions.
Overview of me	thodology and	Searching.				
UNIT - II						
		cal practices are being used by teachers in forma	al and i	nformal	classro	oms
in developing co	ountries. Curric	culum, Teacher education.				
UNIT - III						
		fpedagogicalpractices, Methodology for the indept				en t of
		ther education (curriculumandpracticum) and the				
		t effective pedagogy? Theory of change. Strengt				
		ical practices. Pedagogic theory and pedagogical	ıl appro	aches. T	Teachers	3'
attitudes and bel	iefs and Pedag	ogic strategies.	1			
UNIT - IV						
		nment with classroom practices and follow-up s	support,	Peer su	ipport,	
Support from the						
	mmunity.Curr	iculumandassessment,Barrierstolearning:limited	resourc	esand la	arge clas	SS
sizes		I	l			
UNIT - V	10 . 11		1			
Researchgapsan	atuturedirection	ons:Researchdesign,Contexts,Pedagogy,Teachere	educatio	on,		

Curriculum and assessment, Dissemination and research impact. **Suggested Reading** 

- 1. AckersJ, HardmanF(2001)ClassroominteractioninKenyanprimaryschools, Compare, 31 (2): 245-261.
- $2. \quad A grawal M(2004) Curricular reformins chools: The importance of evaluation, Journal of the control of th$
- 3. Curriculum Studies, 36 (3): 361-379.
- 4. AkyeampongK(2003) Teacher training in Ghana does it count? Multi-site teachereducation



## M.TECH. IN CAD/CAM COURSE STRUCTURE & SYLLABI

research project (MUSTER) country report 1. London: DFID.

- 5. Akyeampong K, LussierK, PryorJ, Westbrook J (2013)Improving teaching and learning of basic maths and reading in Africa: Does teacherpreparation count?International Journal Educational Development, 33 (3): 272–282.
- 6. Alexander RJ(2001) Culture and pedagogy: International comparisons in primary education. Oxford and Boston: Blackwell. Chavan M (2003)ReadIndia: A mass scale, rapid, 'learning to read'campaign.
- 7. www.pratham.org/images/resource%20working%20paper%202.pdf.



<b>Course Code</b>	STRE	ESSMANAGEMENT BY YOGA	L	T	P	C
21DAC201b	2111		2	0	0	0
		Semester	II			
Course Objecti	ves: This course	e will enable students:				
To achie	eve overall health	n of body and mind				
	come stres	•				
<b>Course Outcon</b>	nes (CO): Stude	nt will be able to				
		a healthy body thus improving social health	also			
_	e efficiency					
UNIT - I	-					
Definitions of E	ight parts of yog.	(Ashtanga)				
UNIT - II						
Yam and Niyam						
UNIT - III						
Do`sand Don't's	sin life.					
i) Ahinsa,satya,a	istheya,bramhach	naryaand aparigrahaii) Shaucha,santosh,tapa,s	wadhya	y,ishwa	rpranidl	nan
UNIT - IV						
Asan and Pranay	/am					
UNIT - V						
i)Variousyogposesand theirbenefitsformind &body						
ii)Regularization	nofbreathingtech	niques and its effects-Types ofpranayam				
Suggested Read	ling					
1.'Yogic Asanas	s forGroupTarini	ng-Part-I": Janardan SwamiYogabhyasiMan	dal, Nag	pur		
2. "Rajayogaor conquering the Internal Nature" by Swami Vivekananda, Advaita						
Ashrama (Publication Department), Kolkata						



<b>Course Code</b>	1	ITY DEVELOPMENT		L	T	P	C
21DAC201c	]	ENLIGHTENMENTSK		2	0	0	0
			Semeste	r	I	I	
Course Objecti	ves: This cours	se will enable students:					
To learn	to achieve the	highest goal happily					
<ul> <li>To beco</li> </ul>	me a person wit	th stable mind, pleasing p	ersonality and dete	rminatio	n		
<ul> <li>To awak</li> </ul>	ken wisdom in s	tudents					
Course Outcom	nes (CO): Stude	ent will be able to					
Studyof	Shrimad-Bhagw	vad-Geetawillhelpthestud	entindevelopinghis	personali	tyand a	chieve tl	he
•	goal in life	•	1 0	•	•		
The person	son who has stu	died Geetawilllead the na	ation and mankind t	o peace a	and pros	perity	
_		will help in developing		_	_	1 3	
UNIT - I		1 1 2	1				
Neetisatakam- H	Holistic developi	ment of personality					
Verses-19,20,21		1 3					
Verses-29,31,32		n)					
Verses-26,28,63		,					
UNIT - II							
Neetisatakam- H	Holistic developi	ment of personality					
Verses-52,53,59		•					
Verses-71,73,75	,78(do's)						
UNIT - III							
Approach to day	to day work an	d duties.					
ShrimadBhagwa	ndGeeta:Chapter	2-Verses41,47,48,					
Chapter3-Verses	s13,21,27,35,Ch	apter6-Verses5,13,17,23,	35,				
Chapter 18-Verse	es45,46,48.						
UNIT - IV							,
Statements of ba	asic knowledge.						
	ShrimadBhagwadGeeta:Chapter2-Verses 56,62,68						
Chapter12 -Vers	ses 13, 14, 15, 16, 1	7,18					
Personality of R	olemodel. Shrin	nad Bhagwad Geeta:					
UNIT - V							,
Chapter2-Verses	s 17,Chapter3-V	erses36,37,42,		•			
Chapter4-Verses							
Chapter 18 – Vers	ses37,38,63						
Suggested Read							·
	avadGita"bySwa	amiSwarupanandaAdvait	aAshram(Publication	nDepart	ment),		
Kolkata							
		Niti-sringar-vairagya) b	y P.Gopinath, Ras	ntriyaSar	ıskrit		
Sansthanam,	New Delhi.						



M.TECH. IN CAD/CAM COURSE STRUCTURE & SYLLABI

# OPEN ELECTIVE



Course Code	BUSINESS ANALYTICS	L	T	P	C		
21DOE301c		3	0	0	3		
	Semester			Ш			
Course Objectives:							
	bjective of this course is to give the student a comprehensive under	rstan	ding	of			
business an	alytics methods.						
<b>Course Outcomes</b>	(CO): Student will be able to						
Students wa	ill demonstrate knowledge of data analytics.						
<ul> <li>Students was</li> </ul>	ill demonstrate the ability of think critically in making decisions ba	sed o	on				
<ul> <li>data and de</li> </ul>	ep analytics.						
<ul> <li>Students was</li> </ul>	ill demonstrate the ability to use technical skills in predicative and						
<ul> <li>prescriptive</li> </ul>	e modeling to support business decision-making.						
Students w	ill demonstrate the ability to translate data into clear, actionable ins	ights	S.				
UNIT - I			ture ]	Hrs:			
Business Analysis:	Overview of Business Analysis, Overview of Requirements, Role	of the	e Bus	siness	3		
Analyst.	·						
Stakeholders: the pr	roject team, management, and the front line, Handling Stakeholder	Con	flicts				
UNIT - II			ture ]				
Life Cycles: System	ns Development Life Cycles, Project Life Cycles, Product Life Cyc	cles, l	Requ	irem	ent		
Life Cycles.			•				
UNIT - III		Lec	ture ]	Hrs:			
Forming Requirement	ents: Overview of Requirements, Attributes of Good Requirements	, Typ	es of	f			
	uirement Sources, Gathering Requirements from Stakeholders, Con				ments		
	orming Requirements: Stakeholder Needs Analysis, Decomposition						
	re Analysis, Gap Analysis, Notations (UML & BPMN), Flowcharts						
Flowcharts, Entity-Relationship Diagrams, State-Transition Diagrams, Data Flow Diagrams, Use Case							
Modeling, Business	s Process Modeling						
UNIT - IV			ture ]				
	ments: Presenting Requirements, Socializing Requirements and Ga				ice,		
Prioritizing Require	ements. Managing Requirements Assets: Change Control, Requirer	nents	s Too	ols			
UNIT - V		Lec	ture l	Hrs:			
	Embedded and colleborative business intelligence, Visual data reco						
Storytelling and Da				-			
Textbooks:	······································						
	is by James Cadle et al.						
2. Project Management: The Managerial Process by Erik Larson and, Clifford Gray							
Reference Books:							
	nalytics Principles, Concepts, and Applications by Marc J. Schnied	erjan	s, Da	ıra G			
	ans, Christopher M. Starkey, Pearson FT Press.	3	, -				
	nalytics by James Evans, persons Education.						



**Textbooks:** 

## JAWAHARLAL NEHRU TECHNOLOGICAL UNIVERSITY ANANTAPUR (Established by Govt. of A.P., ACT No.30 of 2008) ANANTHAPURAMU – 515 002 (A.P) INDIA

Course Code	INTERNET OF THINGS (IOT)	L	T	P	С
21DOE301g		3	0	0	3
	Semester		I	II	
		ı			
Course Objective	s: Student will be able				
To study f	fundamental concepts of IoT				
To unders	tand roles of sensors in IoT				
To Learn of	different protocols used for IoT design				
<ul> <li>To be fam</li> </ul>	iliar with data handling and analytics tools in IoT				
<ul> <li>Appreciate</li> </ul>	e the role of big data, cloud computing and data analytics in a typ	ical l	oT s	ystem	1
	s (CO): Student will be able to				
Understan	d the various concepts, terminologies and architecture of IoT sys	tems.	,		
• Use sensor	rs and actuators for design of IoT.				
<ul> <li>Understan</li> </ul>	d and apply various protocols for design of IoT systems				
<ul> <li>Use variou</li> </ul>	as techniques of data storage and analytics in IoT				
<ul> <li>Understan</li> </ul>	d various applications of IoT				
	d APIs to connect IoT related technologies				
UNIT – I		Lec	ture l	Hrs:0	9
Fundamentals of I	oT: Introduction, Definitions & Characteristics of IoT, IoT Archi	itectu	res, I	Physic	cal
& Logical Design	of IoT, Enabling Technologies in IoT, History of IoT, About Thi	ngs i	n IoT	`, The	;
Identifiers in IoT,	About the Internet in IoT, IoT frameworks, IoT and M2M				
UNIT – II		Lec	ture l	Hrs: (	)9
Sensors Networks	: Definition, Types of Sensors, Types of Actuators, Examples an	d Wo	orking	g, IoT	
Development Boar	rds: Arduino IDE and Board Types, RaspberriPi Development Ki	it, RF	FID P	rincip	oles
and components, V	Wireless Sensor Networks: History and Context, The node, Conne	ecting	g nod	les,	
Networking Nodes	s, WSN and IoT.				
UNIT – III				Hrs: (	
Wireless Technolo	ogies for IoT: WPAN Technologies for IoT: IEEE 802.15.4, Zigb	ee, H	<b>ART</b>	, NF	С,
Z-Wave, BLE, Ba	cnet, Modbus.				
IP Based Protocols	s for IoT IPv6, 6LowPAN, RPL, REST, AMPQ, CoAP, MQTT.	Edge	conn	ectiv	ity
and protocols					
UNIT – IV				Hrs: (	
Data Handling& A	Analytics: Introduction, Bigdata, Types of data, Characteristics of	Big	data,	Data	
handling Technologies, Flow of data, Data acquisition, Data Storage, Introduction to Hadoop.					
Introduction to data Analytics, Types of Data analytics, Local Analytics, Cloud analytics and					
applications					
UNIT - V				Hrs: (	)9
~ ~	T: Home Automation, Smart Cities, Energy, Retail Management,	_			
Agriculture, Health and Lifestyle, Industrial IoT, Legal challenges, IoT design Ethics, IoT in					
Environmental Pro	otection.				



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- 1.Hakima Chaouchi, "The Internet of Things Connecting Objects to the Web" ISBN: 978-1-84821-140-7, Wiley Publications
- 2.Olivier Hersent, David Boswarthick, and Omar Elloumi, "The Internet of Things: Key Applications and Protocols", WileyPublications
- 3. Vijay Madisetti and ArshdeepBahga, "Internet of Things (A Hands-on-Approach)", 1<sup>st</sup> Edition, VPT, 2014.
- 4.J. Biron and J. Follett, "Foundational Elements of an IoT Solution", O'Reilly Media, 2016.
- 5. Keysight Technologies, "The Internet of Things: Enabling Technologies and Solutions for Design and Test", Application Note, 2016.

#### **Reference Books:**

- 1.Daniel Minoli, "Building the Internet of Things with IPv6 and MIPv6: The Evolving World of M2M Communications", ISBN: 978-1-118-47347-4, Willy Publication
- 2.Pethuru Raj and Anupama C. Raman, "The Internet of Things: Enabling Technologies, Platforms, and Use Cases", CRC Press

#### Online Learning Resources:

https://onlinecourses.nptel.ac.in/noc17\_cs22/course

http://www.cse.wustl.edu/~jain/cse570-15/ftp/iot\_prot/index.html



<b>Course Code</b>	MECHATRONICS	L	T	P	C
21DOE301h		3	0	0	3
	Semester		I	II	
Course Objecti	ves: Student will be able				
<ul> <li>To study</li> </ul>	y fundamental concepts of Signal condition				
<ul> <li>To unde</li> </ul>	erstand the concepts of precision mechanical systems				
<ul> <li>To Lear</li> </ul>	n different electronic interface subsystems				
To be fa	miliar with microcontrollers overview.				
<ul> <li>To unde</li> </ul>	rstand the concepts of programmable logic controllers				
	nes (CO): Student will be able to				
Underst	and the various concepts, terminologies of Signal condition				
	and the basics electronic interface subsystems				
<ul> <li>Underst</li> </ul>	and and apply various precision mechanical systems				
<ul> <li>Underst</li> </ul>	and various applications of microcontrollers overview				
<ul> <li>Underst</li> </ul>	and the controlling of programmable logic and programmable mo	tion.			
UNIT – I		Lec	ture I	Hrs:0	9
INTRODUCTIO	ON: Definition – Trends - Control Methods: Standalone, PC Based	l (Re	al Ti	me	
Operating System	ms, Graphical User Interface, Simulation) - Applications: SPM, R	obot,	CNO	C, FM	1S,
CIM.					
	DITIONING: Introduction – Hardware - Digital I/O, Analog input -				tion
	Filtering Noise using passive components – Resistors, capacitors -				
	Pamps – Software - Digital Signal Processing – Low pass, high pa				
UNIT – II			ture I		)9
	ECHANICAL SYSTEMS: Pneumatic Actuation Systems - Electro	•			
•	ms - Hydraulic Actuation Systems - Electro-hydraulic Actuation Sy				5
	ew and Nut - Linear Motion Guides - Linear Bearings - Harmonic	l'rans:	missi	on -	
	/ Drive Selection.	_			
UNIT – III			ture I		)9
	INTERFACE SUBSYSTEMS: TTL, CMOS interfacing - Sensor i		_		
	cing – solenoids, motors Isoation schemes- opto coupling, buffer I				
	it breakers, over current sensing, resetable fuses, thermal dissipation	ion -	Powe	er Su	pply
- Bipolar transis		~ 1	1 1		
	CHANICAL DRIVES: Relays and Solenoids - Stepper Motors - Do				
	otors - DC servo motors - 4-quadrant servo drives, PWM's - Pulse	Wiai	.n ivio	oaura	uon
	nency Drives, Vector Drives - Drive System load calculation	Lag	tuna I	Ina. (	20
UNIT – IV	ROLLERS OVERVIEW: 8051 Microcontroller, micro processor st		ture I	пѕ. (	<b>リ</b> ラ
	ng - Analog Interfacing - Digital to Analog Convertors - Analog to			nvort	tore
	Programming –Assembly, C (LED Blinking, Voltage measurement				
UNIT - V	Togramming Tassemory, C ( LLD Diniking, Voltage incastitement		ture I		
	BLE LOGIC CONTROLLERS : Basic Structure - Programming :				
	Relays and Counters - Shift Registers - Master and Jump Controls				
i inici s, inici llal	Relays and Counters - Shirt Registers - Master and Jump Controls	י שמו	u 11a	HUIIII	5-



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Analog input / output - PLC Selection - Application.

PROGRAMMABLE MOTION CONTROLLERS: Introduction - System Transfer Function — Laplace transform and its application in analysing differential equation of a control system - Feedback Devices: Position, Velocity Sensors - Optical Incremental encoders - Proximity Sensors: Inductive, Capacitive,

#### Textbooks:

- 1. A text book of Mechatronics by Er.R.K. RAJPUT., S.CHAND publications
- 2. A text book of Mechatronics by Nitalgour Premchand Mahalik ., McGraw Hill publications

#### Reference Books:

1. A text book of Mechatronics by W.Bolton ., Pearson Publications